

Building a Heuristic for Greedy Search

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Grateful thanks to NSF for support.

This Talk is About Suboptimal Search

Subopt ≠ Optimal

■ Overview

- Hanoi
- GBFS on Hanoi
- TopSpin
- Tile Puzzle
- Summary

GDRC

Conclusion

Greedy Best-First Search (GBFS)

1. best-first on $h(n)$, no $g(n)$. maintains open list.
2. very important in applications (eg planning)
3. building block for anytime algorithms
4. heuristic is crucial

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4. heuristic is crucial

Two central points:

1. **suboptimal is different!**
heuristics for optimal search can be inappropriate
2. **not hard to do better**
Goal Distance Rank Correlation (GDRC)

Example 1/3: 12-Disk 4-Peg Towers of Hanoi

Subopt \neq Optimal

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8+4 PDBs dominates 8+0, right?

Example 1/3: 12-Disk 4-Peg Towers of Hanoi

Subopt ≠ Optimal

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■ **Hanoi**

■ GBFS on Hanoi

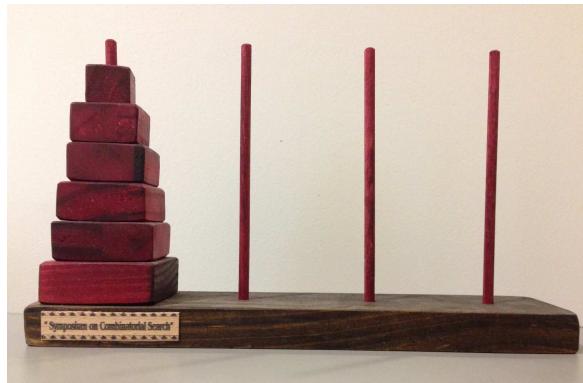
■ TopSpin

■ Tile Puzzle

■ Summary

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8+4 PDBs dominates 8+0, right? Yes, but...

heuristic	node expansions	
	A*	GBFS
8+4 PDBs	2,153,558	36,023
8+0 PDB	4,618,913	771

better for A* ≠ better for GBFS

GBFS Behavior on Towers of Hanoi

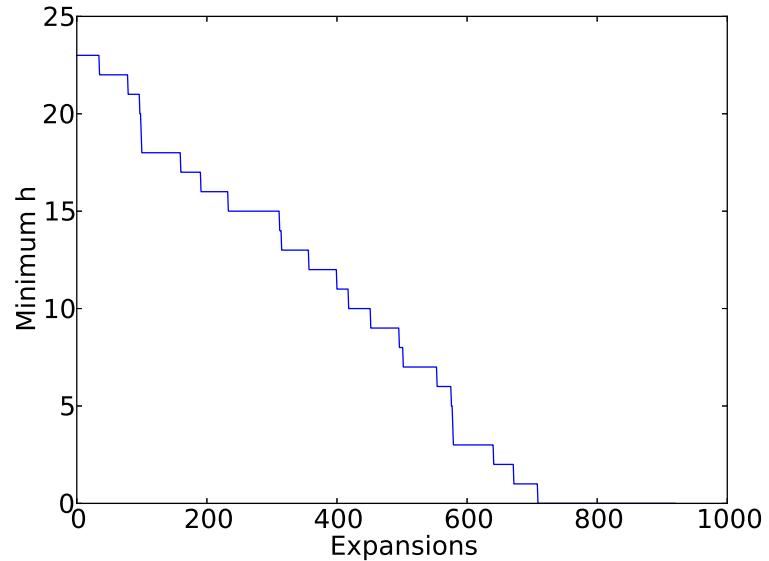
Subopt ≠ Optimal

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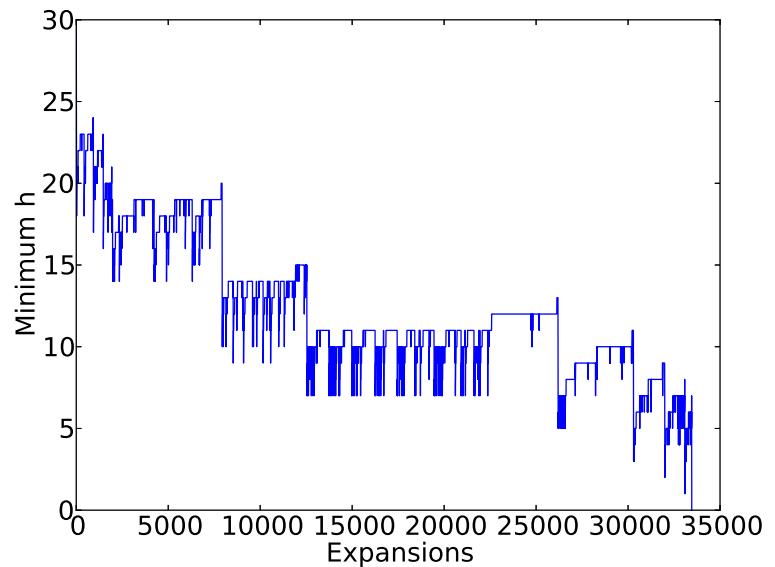
GDRC

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8 PDB



8+4 PDBs



- no local minima
- 256 states at each h value
- low h states can be far from goal
- want 'serialized h values'

Example 2/3: 12-Token 4-Turnstile TopSpin

Subopt ≠ Optimal

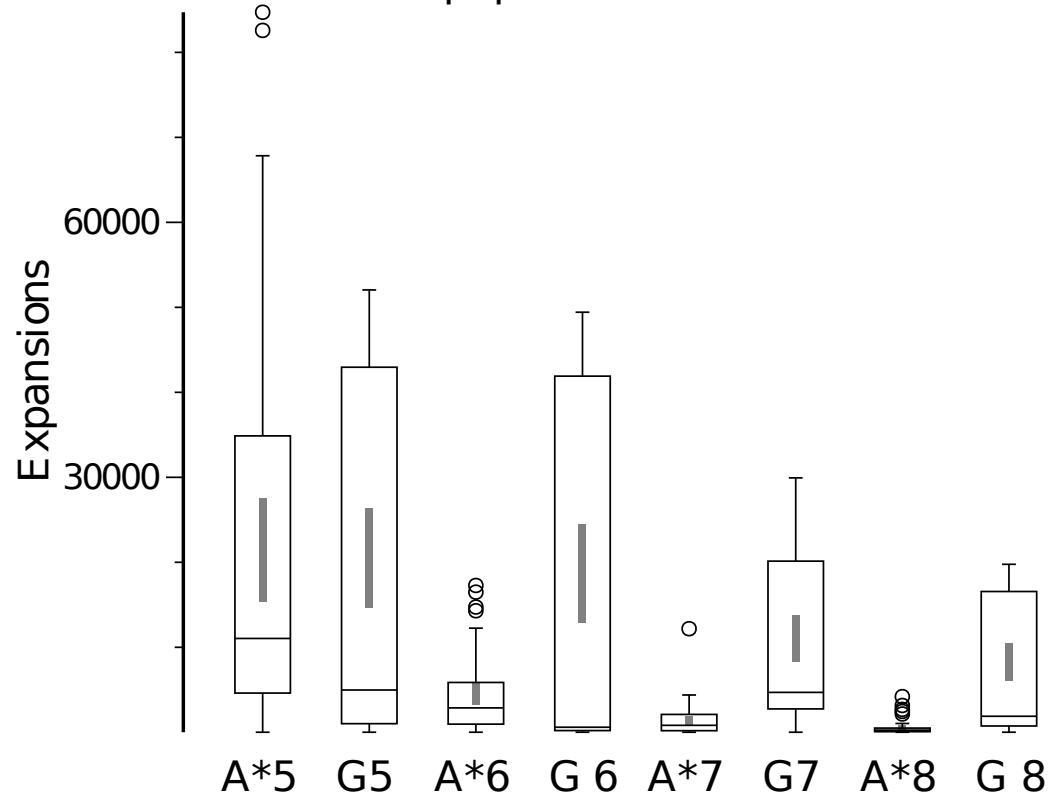
- Overview
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4/12 TopSpin with Different PDB's



many disconnected $h = 0$ regions

Example 3/3: 3×4 Sliding Tile Puzzle

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outer L			
	A	A	3
A	A	A	7
8	9	10	11

one $h = 0$ region

checkered			
	1	A	3
4	A	6	A
A	9	A	11

same size

Example 3/3: 3×4 Sliding Tile Puzzle

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A	9	A	11

same size

abstraction	node expansions	
	GBFS	A*
outer L	258	1,251,260
checkered	11,583	1,423,378
average 6-tile PDB	17,641	1,596,041
worst 6-tile PDB (for GBFS)	193,849	1,911,566

GBFS is sensitive to h
GBFS wants serialized h values

Summary So Far

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Goal Distance Rank Correlation (GDRC)

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GDRC

■ GDRC

■ Building h

■ GDRC h Results

Conclusion

goal distance: number of steps to the goal

rank correlation: how well orderings line up

$$GDRC(h) = \tau(h, d^*)$$

can use all nodes or just a sample near the goal

Goal Distance Rank Correlation (GDRC)

Subopt ≠ Optimal

GDRC

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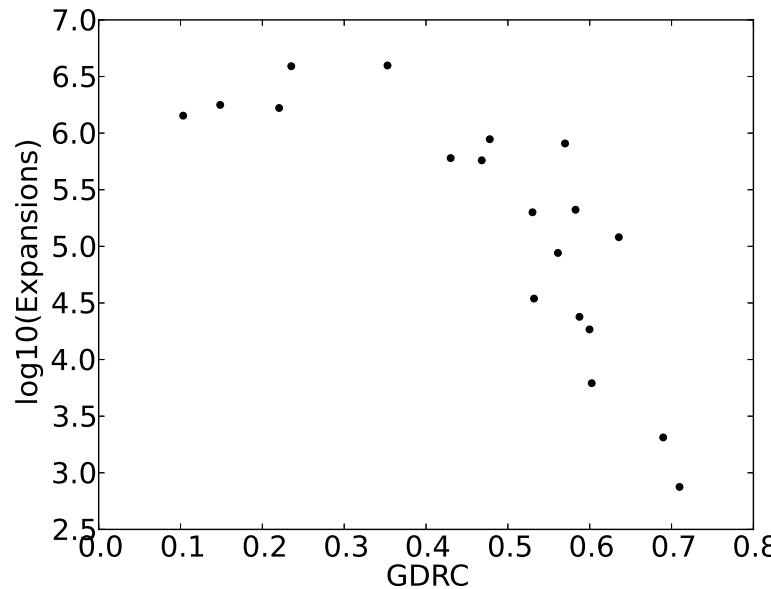
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goal distance: number of steps to the goal
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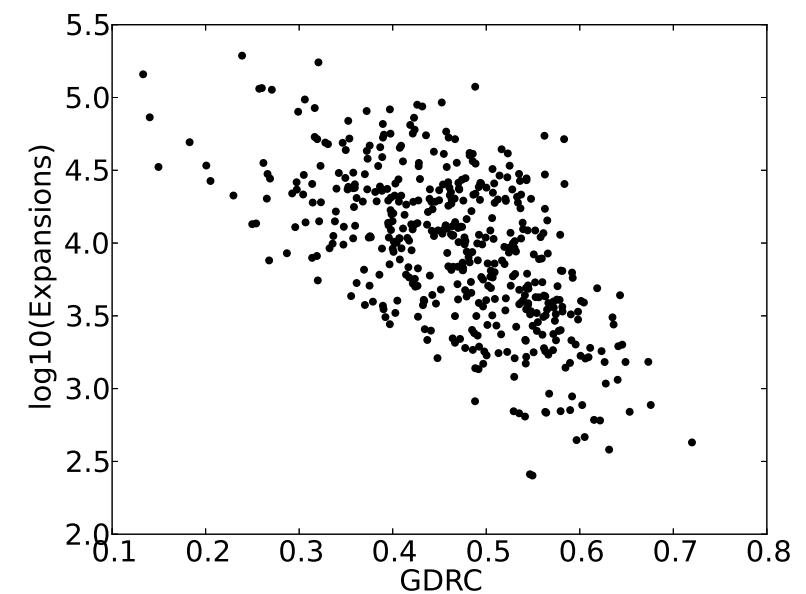
$$GDRC(h) = \tau(h, d^*)$$

can use all nodes or just a sample near the goal

Hanoi



3 × 4 Puzzle



Building a Heuristic for GBFS Using GDRC

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GDRC

■ GDRC

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Conclusion

example: simple hill-climbing in PDB-space

start by abstracting everything

loop until done:

 consider all refinements

 pick one with highest GDRC

Performance of GDRC-Built Heuristics

TopSpin with unit costs: good for both GBFS and A*

TopSpin with some heavy tokens:

Subopt \neq Optimal

GDRC

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Performance of GDRC-Built Heuristics

TopSpin with unit costs: good for both GBFS and A*

TopSpin with some heavy tokens:

PDB	node expansions			avg h value
	GBFS	A*	avg h value	
GDRC-built (contiguous)	411	10,607	52	
built for A* (heavy)	961	411	94	
random	2,387	26,017	48	

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GDRC

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Sliding Tiles:

abstraction	GBFS	A*
outer L	258	1,251,260
checkered	11,583	1,423,378
average 6-tile PDB	17,641	1,596,041
instance-specific	8,530	480,250
GDRC-built (4th/462)	427	1,197,789

GDRC-built heuristics seem well-tuned for GBFS!

Subopt ≠ Optimal

GDRC

■ GDRC

■ Building h

■ GDRC h Results

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Conclusions

Subopt ≠ Optimal

GDRC

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■ Conclusions

suboptimal is different!

- more sensitive to h
- better h for optimal can be worse for greedy
- needs its own theory and methods

not hard to do better!

Goal Distance Rank Correlation (GDRC)

- estimates seem effective
- can search space of PDBs

this area is wide open!



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GDRC

Conclusion

Extra Slides

■ More results

Extra Slides

More results

foo

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