

CSPs

Combinatorial
Optimization

Adversarial Search

1 handout: slides
730W blog entries were due

You think you know when you can learn, are more sure when you can write, even more when you can teach, but certain when you can program.

EOLQs

CSPs

Combinatorial
Optimization

Adversarial Search

CSPs

- Other Problems
- Types of Problems
- 'Heuristics'
- Example Results
- MAC
- Other Algorithms
- Break

Combinatorial
Optimization

Adversarial Search

Constraint Satisfaction Problems

Types of Search Problems

CSPs

Other Problems

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Combinatorial Optimization

Adversarial Search

- Shortest-path (vacuum, tile puzzle, M&C)
 - ◆ given operators and their costs
 - ◆ want least-cost path to a goal
 - ◆ goal depth/cost unknown
- Constraint satisfaction (map coloring, n -queens)
 - ◆ any goal is fine
 - ◆ fixed depth
 - ◆ explicit constraints on partial solutions

Heuristics for CSPs

CSPs

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- **Types of Problems**
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Combinatorial Optimization

Adversarial Search

Variable choice: choose most constrained variable (smallest domain)

- want to keep tree small, failing quickly

Value choice: try least constraining value first (fewest removals)

- might as well succeed sooner if possible

Example Results

CSPs

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Combinatorial Optimization

Adversarial Search

	BT	FC	FC+MCV
USA	> 1M	2K	60
n-Queens	> 40M	> 40M	820K
Zebra	3.9M	35K	500
Random 1	420K	26K	2K
Random 2	940K	77K	15K

Maintaining Arc Consistency

CSPs

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Combinatorial Optimization

Adversarial Search

Ensure every value for x has a legal value in all neighbors y . If one doesn't, remove it and ensure consistency of all y .

Maintaining Arc Consistency

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Adversarial Search

Ensure every value for x has a legal value in all neighbors y . If one doesn't, remove it and ensure consistency of all y .

while Q is not empty

$(x, y) \leftarrow \text{pop } Q$

 if **revised** (x, y) then

 if x 's domain is now empty, return failure

 for every other neighbor z of x

 push (z, x) on Q

revised (x, y)

revised \leftarrow false

 foreach v in x 's domain

 if no value in domain of y is compatible with v

 remove v from x 's domain

revised \leftarrow true

 return *revised*

Other Algorithms for CSPs

CSPs

- Other Problems
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■ MAC

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Combinatorial Optimization

Adversarial Search

- (Conflict-directed) Backjumping
- Dynamic backtracking
- Randomized restarting

Course projects!

Break

CSPs

- Other Problems
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■ Other Algorithms

- Break

Combinatorial Optimization

Adversarial Search

- what is a course project?
- asst 1 going out on Wed

CSPs

Combinatorial
Optimization

■ Types of Problems

■ Hill-Climbing

Adversarial Search

Combinatorial Optimization

Types of Search Problems

CSPs

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Optimization

■ Types of Problems

■ Hill-Climbing

Adversarial Search

- Shortest-path (M&C, vacuum, tile puzzle)
 - ◆ want least-cost path to a goal
 - ◆ goal depth unknown
 - ◆ given operators and their costs
- Constraint satisfaction (map coloring, n -queens)
 - ◆ any goal is fine
 - ◆ maximum depth = number of variables
 - ◆ given explicit constraints on variables
- Combinatorial optimization (TSP, max-CSP)
 - ◆ want least-cost goal
 - ◆ maximum depth = number of variables
 - ◆ every leaf is a solution

Hill-Climbing

CSPs

Combinatorial
Optimization

■ Types of Problems

■ Hill-Climbing

Adversarial Search

$Sol \leftarrow$ some random solution (probably poor quality).

Do *limit* times

$New \leftarrow$ random **neighbor** of Sol .

If New better than Sol ,
then $Sol \leftarrow New$.

Hill-Climbing

CSPs

Combinatorial
Optimization

■ Types of Problems

■ Hill-Climbing

Adversarial Search

$Sol \leftarrow$ some random solution (probably poor quality).

Do *limit* times

$New \leftarrow$ random **neighbor** of Sol .

If New better than Sol ,
then $Sol \leftarrow New$.

Elaborations: best neighbor (aka gradient-descent)
restarts
simulated annealing
population (GAs, 'go with the winners')

CSPs

Combinatorial
Optimization

Adversarial Search

- Another Type
- Minimax
- Tic-tac-toe
- Improvements
- EOLQs

Adversarial Search

Another Twist on Search

CSPs

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Adversarial Search

- Another Type
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- Improvements
- EOLQs

- Shortest-path (M&C, vacuum, tile puzzle)
 - ◆ want least-cost path to goal at unknown depth
- Constraint satisfaction (map coloring, n -queens)
 - ◆ any goal that satisfies constraints (fixed depth)
- Combinatorial optimization (TSP, max-CSP)
 - ◆ want least-cost goal (fixed depth)
- Decisions with an adversary (chess, tic-tac-toe)
 - ◆ adversary might prevent path to best goal
 - ◆ want best assured outcome

Adversarial Search: Minimax

CSPs

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■ Another Type

■ Minimax

■ Tic-tac-toe

■ Improvements

■ EOLQs

Each *ply* corresponds to half a *move*.

Terminal states are labeled with value.

Can also bound depth and use a *static evaluation function* on non-terminal states.

Evaluation for Tic-tac-toe

CSPs

Combinatorial
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■ Another Type

■ **Minimax**

■ Tic-tac-toe

■ Improvements

■ EOLQs

A *3-length* is a complete row, column, or diagonal.

value of position = ∞ if win for me,

or = $-\infty$ if a win for you,

otherwise = $\#$ 3-lengths open for me –
 $\#$ 3-lengths open for you

Tic-tac-toe: two-ply search

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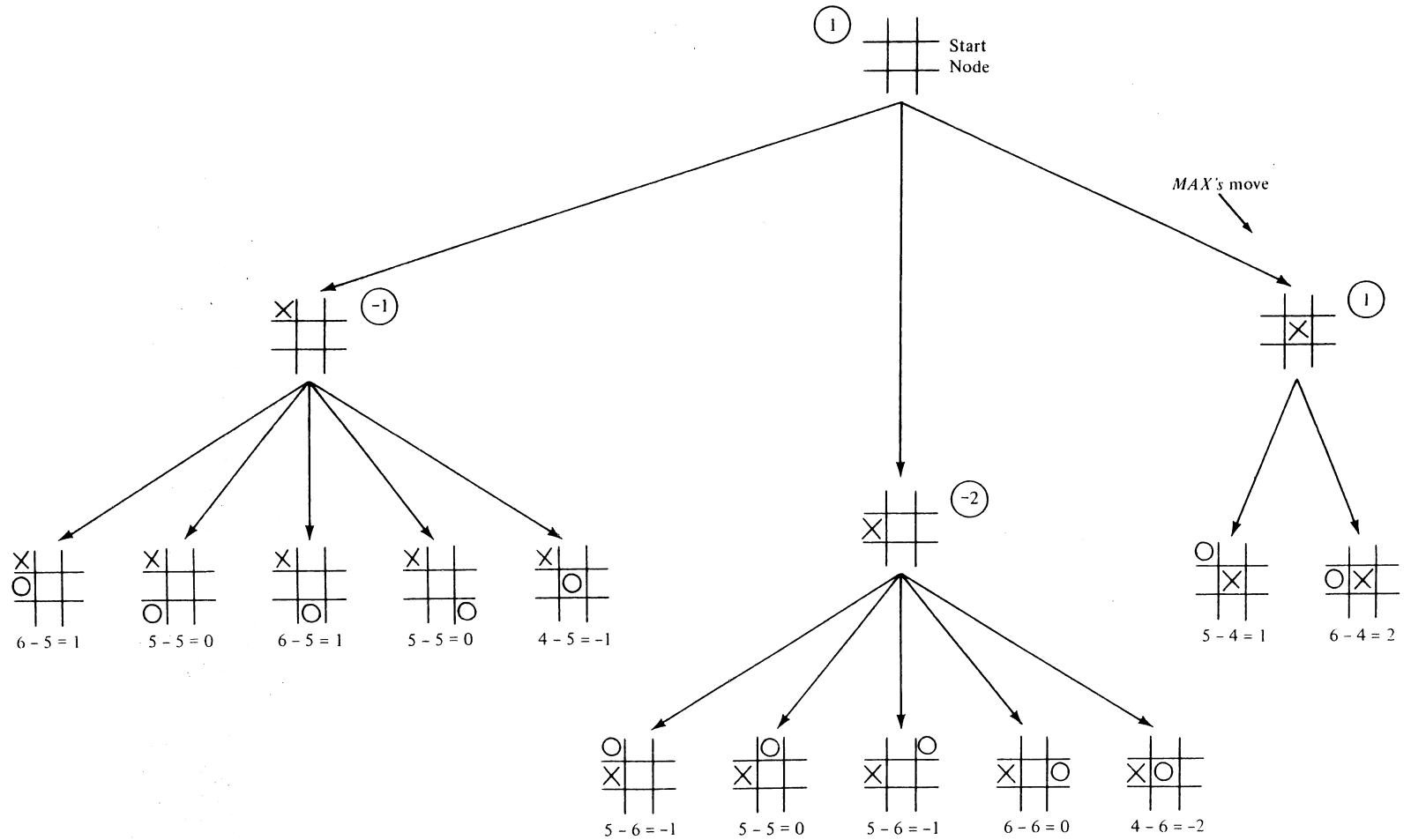


Fig. 3.8 Minimax applied to tic-tac-toe (stage 1).

Tic-tac-toe: second move

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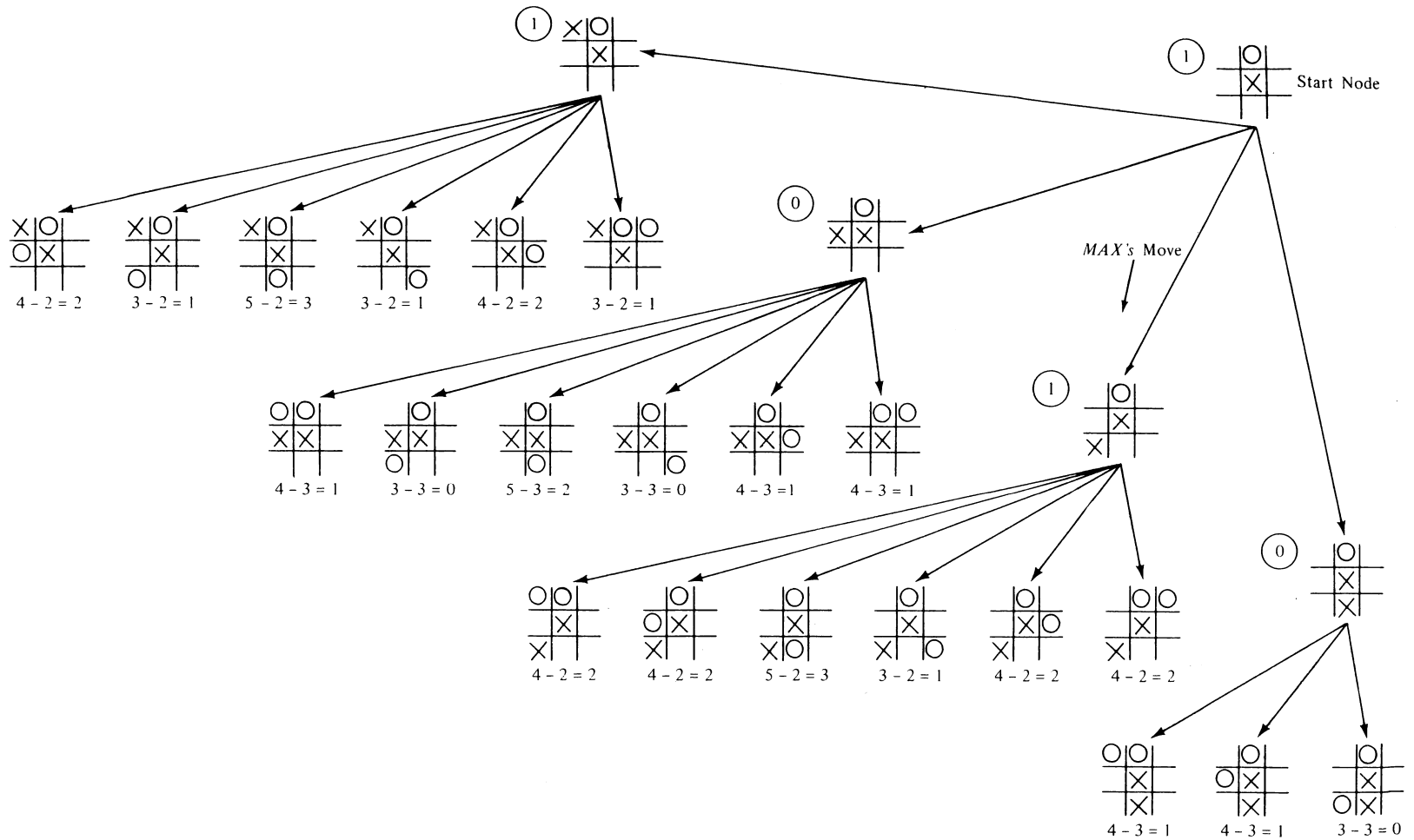


Fig. 3.9 Minimax applied to tic-tac-toe (stage 2).

Tic-tac-toe: third move

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■ Improvements

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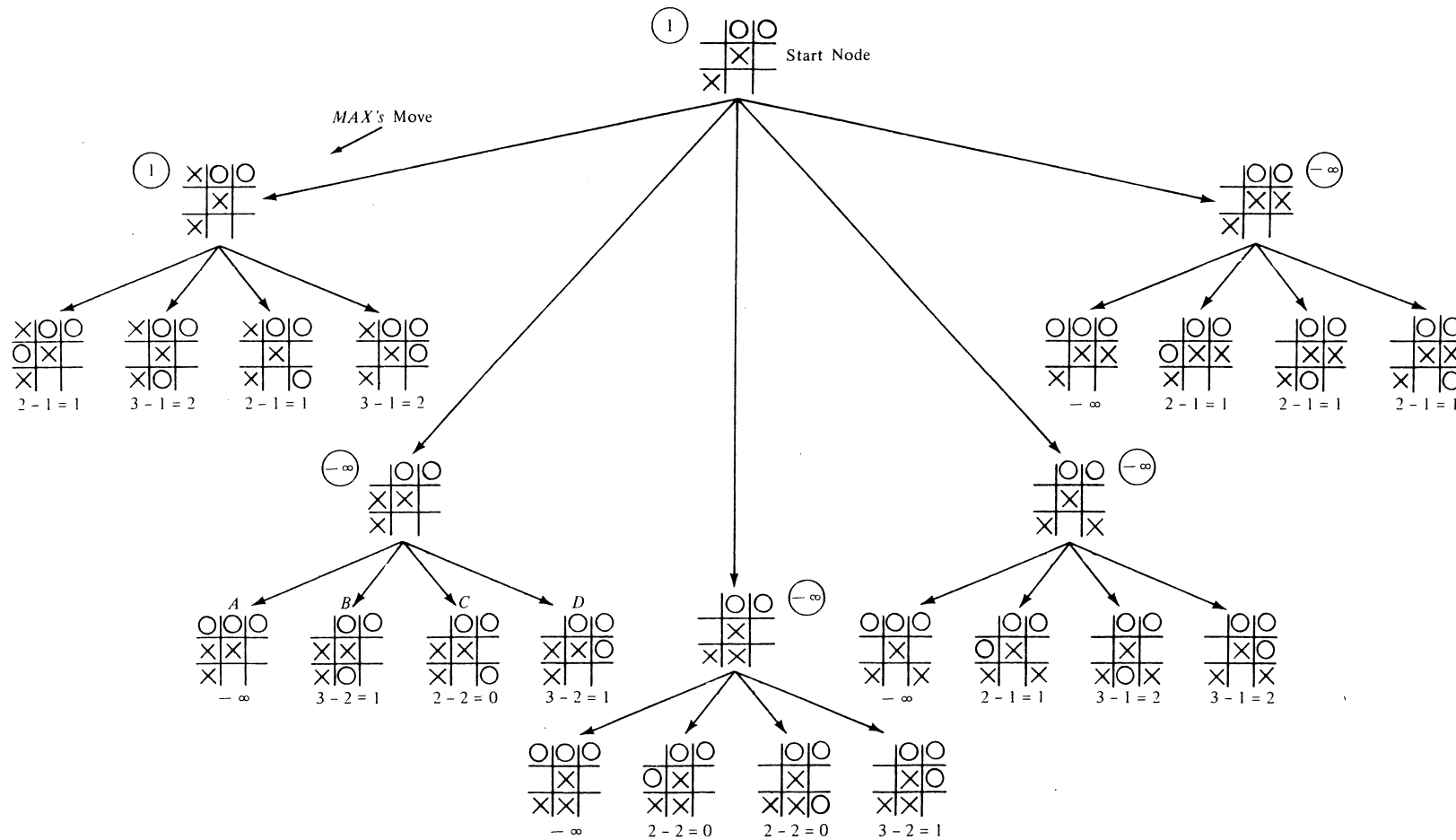


Fig. 3.10 Minimax applied to tic-tac-toe (stage 3).

Improving the Search

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■ Another Type

■ Minimax

■ Tic-tac-toe

■ Improvements

■ EOLQs

- partial expansion, SEF
- symmetry ('transposition tables')
- search more ply as we have time (De Groot figure)
- avoid unnecessary evaluations

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■ Minimax

■ Tic-tac-toe

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Please write down the most pressing question you have about the course material covered so far and put it in the box on your way out.

Thanks!