

■ Break

HMMs

1 handout: slides
final blog entries were due

Break

■ Break

HMMs

- Wed May 2: HMMs, unsupervised learning, applications
- Mon May 7: special guest Scott Kiesel on robot planning
- Wed May 9, 9-noon: project presentations
- Thur May 10, 8am: paper drafts (optional for some)
- Fri May 11, 10:30: exam 3 (N133)
- Tues May 15, 3pm: papers (one hardcopy + electronic PDF)

menu?

- Break

- HMMs**

- Models

- The Model

- Viterbi Decoding

- Random

- EOLQs

Hidden Markov Models

Probabilistic Models

■ Break

HMMs

■ Models

■ The Model

■ Viterbi Decoding

■ Random

■ EOLQs

MDPs:

Naive Bayes:

k -Means:

Markov chain:

Hidden Markov model:

A Hidden Markov Model

■ Break

HMMs

■ Models

■ The Model

■ Viterbi Decoding

■ Random

■ EOLQs

$$P(x_t = j) = \sum_i P(x_{t-1} = i)P(x_t = j|x_{t-1} = i)$$

$$P(e_t = k) = \sum_i P(x_t = i)P(e = k|x = i)$$

More concisely:

$$P(x_t) = \sum_{x_{t-1}} P(x_{t-1})P(x_t|x_{t-1})$$

$$P(e_t) = \sum_{x_t} P(x_t)P(e|x)$$

Viterbi Decoding

■ Break

HMMs

■ Models

■ The Model

■ Viterbi Decoding

■ Random

■ EOLQs

given: transition model $T(s, s')$

sensing model $S(s, o)$

observations o_1, \dots, o_T

find: most probable s_1, \dots, s_T

initialize $S \times T$ matrix v with 0s

$v_{0,0} \leftarrow 1$

for each time $t = 0$ to $T - 1$

 for each state s

 for each new state s'

 score $\leftarrow v_{s,t} \cdot T(s, s') \cdot S(s', o_t)$

 if score $> v_{s',t+1}$

$v_{s',t+1} \leftarrow$ score

 best-parent(s') $\leftarrow s$

trace back from s with $\max v_{s,T}$

Random

■ Break

HMMs

■ Models

■ The Model

■ Viterbi Decoding

■ Random

■ EOLQs

applications

unsupervised learning: dimensionality reduction

■ Break

HMMs

■ Models

■ The Model

■ Viterbi Decoding

■ Random

■ EOLQs

- What question didn't you get to ask today?
- What's still confusing?
- What would you like to hear more about?

Please write down your most pressing question about AI and put it in the box on your way out.

Thanks!