

CS 730/830: Intro AI

Regression

POP

Regression

- Aristotle
- Regression
- Grocery World
- Comparison
- Break

POP

Regression

Aristotle's Means-ends Analysis

Regression

Aristotle

Regression

Grocery World

Comparison

Break

POP

We deliberate not about ends, but about means. For a doctor does not deliberate whether he shall heal, nor an orator whether he shall persuade, nor a statesman whether he shall produce law and order, nor does any one else deliberate about his end. They assume the end and consider how and by what means it is attained, and if it seems easily and best produced hereby; while if it is achieved by one means only they consider how it will be achieved by this and by what means *this* will be achieved, till they come to the first cause, which in the order of discovery is last. . . and what is last in the order of analysis seems to be first in the order of becoming. And if we come on an impossibility, we give up the search, for example, if we need money and this cannot be got; but if a thing appears possible we try to do it.

— Aristotle, *Nicomachean Ethics*, 350BC

Regression

Regression

■ Aristotle

■ Regression

■ Grocery World

■ Comparison

■ Break

POP

Note that STRIPS has full initial state, partial goal state (= set).
Search over sets of states!

Initial node: set of states in which goal is true

Applicable: at least one effect present, deletes not present,
non-deleted preconditions present

Child node: remove adds, add preconditions

Goal node: subset of initial state

Doesn't assume domain has inverse actions

Lower branching factor?

Larger space (3^n vs 2^n)

Grocery World

Regression

■ Aristotle

■ Regression

■ Grocery World

■ Comparison

■ Break

POP

Initial: At(Home), Sells(HWS, Drill), Sells(SM, Milk), Sells(SM, Bananas)

Go (here,there)

Pre: At(here)

Post: At(there), \neg At(here)

Buy(store,x)

Pre: At(store), Sells(store, x)

Post: Have(s)

Goal: At(Home), Have(Drill), Have(Milk), Have(Bananas)

Comparison

Regression

- Aristotle
- Regression
- Grocery World
- Comparison
- Break

POP

Forward: states

- – irrelevant states
- + reachable states
- + state known: strong heuristic, expressivity
- – branching factor

Backward: sets of states

- + relevant states
- – unreachable states
- – partial states: larger space, weaker heuristic, expressivity

Break

Regression

- Aristotle
- Regression
- Grocery World
- Comparison

■ Break

POP

- asst 8
- projects: final proposals, presentations, papers
- note asst 9 due on a Tuesday

Regression

POP

- POP
- Grocery World
- Search
- Main Loop
- Finding Threats
- Principles
- Comparison
- EOLQs

Partial-order Planning

Partial-order Planning

Regression

POP

■ POP

■ Grocery World

■ Search

■ Main Loop

■ Finding Threats

■ Principles

■ Comparison

■ EOLQs

Initial node: empty plan

Branch on all achievers of selected precondition

Branch on all threat resolutions

Goal node: plan without open preconditions

Grocery World

Regression

POP

■ POP

■ Grocery World

■ Search

■ Main Loop

■ Finding Threats

■ Principles

■ Comparison

■ EOLQs

Initial: At(Home), Sells(HWS, Drill), Sells(SM, Milk), Sells(SM, Bananas)

Go (here,there)

Pre: At(here)

Post: At(there), \neg At(here)

Buy(store,x)

Pre: At(store), Sells(store, x)

Post: Have(s)

Goal: At(Home), Have(Drill), Have(Milk), Have(Bananas)

Searching Plan-space

Regression

POP

■ POP

■ Grocery World

■ Search

■ Main Loop

■ Finding Threats

■ Principles

■ Comparison

■ EOLQs

Principle of least commitment

plan: bindings, temporal links, causal links

complete: every precondition achieved, all vars instantiated

consistent: no temporal or binding contradictions

threat: potential clobber

refinement = adding actions and links

Partial-order Planning

Regression

POP

■ POP

■ Grocery World

■ Search

■ Main Loop

■ Finding Threats

■ Principles

■ Comparison

■ EOLQs

initialize plan to empty

loop

pick unachieved precondition

find or **add** action to establish it

if no such, backtrack

add causal and temporal link

for every threat

put threat before achiever **or** after dependent

if inconsistent, backtrack

for possible threats

add inequality constraint

Finding Threats

Regression

POP

- POP
- Grocery World
- Search
- Main Loop
- Finding Threats
- Principles
- Comparison
- EOLQs

For each new effect and each causal link

check if effect unifies with \neg (condition of link)

For each new causal link and each step

check if effect of step unifies with \neg (condition of link)

- refinement = adding actions and links
- achieve, establish, produce
- promote, demote, protect
- inequality, separation, non-codesignation

Principles

Regression

POP

■ POP

■ Grocery World

■ Search

■ Main Loop

■ Finding Threats

■ Principles

■ Comparison

■ EOLQs

- Causal links
 - ◆ Limits search to relevant actions
 - ◆ Easy plan modification and explanation

- Least commitment
 - ◆ Flexibility in choosing what to branch on
 - ◆ Limits backtracking
 - ◆ Smaller search space
 - ◆ Allows more pruning of implicit plans
 - ◆ Hard to find a good heuristic

Comparison

Regression

POP

- POP
- Grocery World
- Search
- Main Loop
- Finding Threats
- Principles
- Comparison
- EOLQs

Forward: states

- + state known: strong heuristic, expressivity
- – branching factor
- – irrelevant states

Backward: sets of states

- + relevant states
- – partial states: larger space, weaker heuristic, expressivity

Partial-order: plans

- + small space
- +/– least commitment
- – poor heuristics

Regression

POP

- POP
- Grocery World
- Search
- Main Loop
- Finding Threats
- Principles
- Comparison

■ EOLQs

- What question didn't you get to ask today?
- What's still confusing?
- What would you like to hear more about?

Please write down your most pressing question about AI and put it in the box on your way out.

Thanks!