

## Implementing Go Channels

The Go philosophy is that goroutines should avoid reading & writing the same memory locations.

Instead goroutines should share data by exchanging messages.

Channels are objects that control the sharing of messages — can send to a channel  
can receive from a channel

Channels are typed, meaning a particular channel will always facilitate the exchange of the same kind of message. For us this means the length of the message sent or received by a particular channel will be the same.

Channels can contain a buffer with a fixed capacity — the maximum number of messages the channel can contain.

A channel with a non-zero capacity allows senders to possibly not block.

## zero-capacity channel

sender must block until  
receiver is ready

receiver must block until  
sender is ready

If multiple senders are blocked  
or multiple receivers are blocked,  
then they wait in a FIFO  
queue.

Consider the case of the sender  
arriving first:

sender will block - recording  
its data address in its GCIB  
block by moving it ~~self~~<sup>GCIB</sup> from  
the ready list and inserting  
it at the end of the queue  
for the channel  
and it will yield to the  
next coroutine in the  
ready list

If none, deadlock - panic  
When receiver arrives, it  
checks queue to see if there

is a waiting sender  
if so, it copies the data from  
the sender using the data address  
in the sender's GCB  
(the data ~~field~~ needs to be a  
field in ~~the~~ the struct  
for the channel)  
then it moves the sender's GCB  
to the end of the ready list

the case of the receiver arriving  
first is similar - when  
the sender arrives, it will  
copy its data to the receiver  
using the data address field  
of the receiver's GCB. And  
then it will unblock the  
receiver.

### closing channels

a channel can be closed

need a  
field in  
GCB for  
this purpose

waiting receivers should be unblocked  
given "two messages" and  
a return value of  $\pm 0$ .

need a waiting senders should be unblocked  
field in the GCB for this purpose  
and told to panic if/when they execute

### nil channel

represented as a NULL channel handle

a send/receive from a nil channel  
causes the goroutine to block forever

### validating channel not zero!

put a "magic number" at the front of your struct that implements a channel

use this to do a rudimentary check  
that a handle is valid  
if the check fails, panic

## nos-2nd-capacity channels

channel  
capacity  
should be  
field in  
struct

when malloc-ing channel struct,  
must also malloc a buffer  
must put fields in channel struct  
to control the buffer:  
ptr to buffer  
number of data items currently  
in the buffer (the channel length)  
where to insert the next data item  
where to remove the next data item

### send

check if waiting receiver

if so, buffer must be empty so  
exchange is like for 0-capacity channel  
check if room in buffer

if so, insert into buffer and  
do not block

otherwise must block again

when goroutine executes it should  
check if channel was closed  
wh. t was blocked

if so, panic

### receive

if there is data client in the buffer,  
take it from buffer

if there is a sender blocked  
put its data client into  
the buffer & unblock the  
sender

if there is a waiting sender  
then this is a zero-capacity channel  
otherwise just block

when goroutine executes again it  
should check if channel was  
closed when it was blocked  
if so, return  $\emptyset$  instead of 1.

### other primitives

`cap` channel - return the channel  
capacity

~~len~~ channel  
~~length~~ - return the number of  
items in the channel  
buffer

`free` channel - free the memory for  
the channel

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clean Goroutines — frees the  
memory used by all goroutines  
note: does not free memory used  
by channels