Multiresolution Data Problem Space/Error Tradeoffs for Represent same data at different resolutions Lossy Wavelet Reconstruction Each lower resolution should take less space will introduce additional error into the representation Research goals Jonathan Frain and R. Daniel Bergeron Computer Science, University of New Hampshire explore new approaches for generating low resolution data quantify space/error tradeoffs VDA 2012 VDA 2012 2 1

Our approach

3D wavelet transformations produce 8 sets of wavelet coefficients: 1 <u>summary</u>, 7 <u>detail</u>

Summary coefficients can be easily used to approximate original data: ¹/₈ the size, and some error

Can reconstruct original data with <u>no error</u> using all 7 sets of detail coefficients, but no space savings

Can we use <u>subsets</u> of detail coefficients to get better space/error tradeoffs?

Outline

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Wavelet overview

Lossy reconstruction

- Traditional approaches
- Our scheme
- Evaluation process
- Results

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Wavelet Overview

Wavelets provide a powerful tool for multiresolution data generation

1-dimensional wavelet transformation

N data values map to N/2 summary values and N/2 detail values

summary data is the lower resolution representation

detail data encapsulates the "error"

lossless transformation: can reconstruct the original data from the summary and associated detail

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Multiresolution 1D Wavelet

| Original Data | | |
|---------------|---------|--|
| Summary | | |
| Summary | eran () | |
| Sum Det | | |

Each summary is a coarser representation of previous.

Can reconstruct higher resolution exactly (with some numerical roundoff error) from lower resolution summary and detail.

If ignore detail, can reconstruct approximation of higher resolution from lower summary (assuming 0 for detail).

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2D Wavelets

Given a 2-D array of input data

- apply 1D wavelet to each row
- apply 1D wavelet to resulting columns

Summary is 1/4 input size

- 3 sets of detail coefficients
- SD: Summary of Detail
- DS: Detail of Summary
- DD: Detail of Detail





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SD: summary of detail

3D Wavelets

Extend 2D: apply 1D wavelets in 3 directions

across all rows in all planes down all columns in all planes into all "piles" at each row/column position Results in:

summary that is ¹/₈ size of original 7 details: SSD, SDS, SDD, DSS, DSD, DDS, DDD



Traditional Lossy Reconstruction

Easiest: use only summary; set all details to 0

low memory; high error

Save *n* highest magnitude coeff, set rest to 0 [Matias et al.] need to store coord position along with each wavelet coefficient Save highest impact coefficients [Sacharidis et al.]

Tree structure yields more efficient coord position storage Extension to 2D and 3D not obvious

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Precision Reduction

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Wavelet detail coefficients

represent error components magnitudes are generally *much smaller* than data values (and summary coefficients)

Try representing them as byte, rather than float determine <u>range</u> of a subband of wavelet coefficients use a byte to represent a mapping into range linear mapping is simplest

software allows an arbitrary "lookup" table to be used

Lossy Reconstruction New Approach

Examine influence of the different detail blocks (subbands)

Do some blocks encapsulate more error than others?

If so, is there any consistency among different data sets?

Can coefficient *precision reduction* yield better space/error tradeoffs

Would 4 sets of detail coefficients stored as bytes yield less error than 1 set stored as float?

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Evaluation Platform

Software that can

apply Haar wavelet at multiple levels

compute Haar wavelet reconstruction using arbitrary subset of wavelet coefficient blocks (subbands)

compute a variety of error measures for reconstructed data Sum absolute point error (SAPE) Sum squared error (SSE) evaluated at each point of original data Root mean squared absolute error (RMSE) Normalized RMSE Max error Average absolute error

Evaluation Process

For a variety of data sets

Apply 3 levels of Haar wavelet transforms For each level, reconstruct data at original resolution use each coefficient block by itself (8 reconstructions) choose block with the lowest error: Best1 reconstruct data with Best1 plus each of the other 7 choose block pair with lowest error: Best2 repeat to get Best3, Best4, Best5, Best6 and Best7

For each "best" combination, try precision reduction reconstruct / compute error using a <u>byte</u> for detail coefficients reconstruct / compute error using a <u>byte</u> for all coefficients

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Evaluation Criteria

Brute force implementation; no effort to optimize (or even

For very large files in a network environment, communication

Even local disk I/O is likely to be more critical than CPU time

Error Measures

Software computes 6 different error measures

Max absolute best for defining precision needed for guaranteeing minimum error [Woodring et al.], but not very good measure of overall error

We focused on *sum absolute point error* (SAPE) and *sum squared error* (SSE)

In practice, want spatial region-based error, not one value

Primary Data Sets

Primary data sets

cthead - 3D CAT scan of a head *OpenGGCM* - 3D simulation of solar winds as they approach the Earth; used 1 attribute from a typical "interesting" time step

Only measured error and space

improve) software efficiency

costs are dominant

Did not consider computation costs





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Secondary Data Sets

We also tested other data sets

Other time steps from OpenGGCM simulation Walnut from voreen.org, European Inst of Molecular Imaging Stagbeetle from TU Wien, Austria Stanford brain

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Summary of (reported) tests

Apply 3 levels of wavelets to *cthead* and *openGGCM* report error for each level

Detail Elimination with full precision

Order detail coefficients by reconstruction error when using SSS and exactly 1 detail subband (Best 2)

Identify Best 3, Best 4, ..., Best 7 subbands Show error reduction for best 1-8 subbands: how <u>much</u> does each subband reduce the error?

Detail elimination with precision reduction (PR) Repeat above steps apply PR for details and for all coeff. Show space/error tradeoffs

What do we want to learn?

Do the wavelet subbands contribute (significantly) different information to the reconstruction?

I.e., how much error is introduced for each subband that is <u>not</u> used in the reconstruction?

If so, are these differences consistent:

for different wavelet resolution levels for same data set? for different data sets?

Can wavelet coefficients be stored at lower precision without significant increase in error?

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Detail elimination (no PR) Best 2 : Ct Scan

Best wavelet subband is always summary (SSS) So, looking for "best" detail subband



Subband region <u>order</u> is same for all resolutions: DSS→SDS→SSD→DDS→DSD→SDD→DDD

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PR for GGCM data Open GGCM - SAPE for Three Levels with and without Precision Reduction 2.00E+00 COMPRESS DETAILS COMPRESS ALL 1.80E+007 1.60E+007 1.40E+007 1.20E+007 AN 1.00-6 00F+00F 4.00E+006 2 00F+00F 0.00F+000

Missing coeff error quickly dominates precision reduction error VDA 2012 29

Error vs Space: CT

For a fixed size, find option with least error Or, for a fixed error find option requiring least space CAT SCAN - Error vs. Space for Three Levels with and without Precision Reduction 25000 20000 SAPE 150000 100000 50000 0.2 0.4 Relative Size 0.6 0.7 0.9 Space $\frac{1}{8}$ of original: resolution 3, with 3 detail subbands with all data using reduced precision

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Error vs Space

We have a range of options for representing data

3 resolution levels

0-7 detail subbands

without precision reduction, applying precision reduction to the details, and applying precision reduction to all coefficients

Graphs show 24 points representing 3 resolution levels and 8 choices of wavelet subbands -ordered by increasing size

The 3 precision reduction options are graphed separately

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Error vs Space: GCCM



Error vs Space: GCCM

With tail truncated



Secondary Data Sets

Stag beetle Best2 order: DSS→SDS→SSD→others Best3 - Best7: match Best2 order Stanford brain Best2 order: DSS→SDS→SSD→others Best3 - Best7: match Best2 order Walnut Best2 order: SDS→SSD→DSS→SDD→others Best3 - Best7: Res 2 and 3 reversed DSS and SDD Two different GGCM time steps Consistent with other GGCM results

Consistency of Results CT vs GGCM

2-way order: identical

Best2 - Best4 order matches 2-way order

Best5 - Best7 order: some differences with 2-way

but magnitude of the differences were very small

Precision reduction results very similar <u>except</u> compressing summary more successful for CT data

may be an artifact of our implementation: CT data is normalized to 0,1

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Observations

Data tests we have run so far are encouraging

Wavelet subbands aren't all created equal

Detail elimination results are reasonably consistent

Best2 subband ordering is a good approximation to Best3-Best7 order

Without any pre-processing, DSS, SDS and SSD are good candidates for first 3 subbands; though order is not always optimal, it's good

Precision reduction results are reasonably consistent

Could provide basis for heuristics

Conclusions

Using selected detail subbands for data reconstruction can provide better space/error tradeoffs than traditional approaches

Representing detail coefficients as bytes can provide significant space savings for only small additional error

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Future Work

Re-implement precision reduction

Incorporate a local error model as part of detail elimination and precision reduction

Test other data sets

Devise more efficient reconstruction

Incorporate these ideas into an adaptive resolution / multiresolution software framework

Weaknesses

| | Our precision reduction implementation is naive it generates only 1 mapping table for all subbands; there should be a separate table for each subband |
|----------|---|
| | we use a simple linear mapping; a nonlinear mapping might yield lower error |
| | Are our test data sets really representative? |
| | CT and MR data has pretty low underlying precision (12-14 bits); is that skewing the results? |
| | all data sets we tested have lots of "empty" space. |
| | A single global measure for error is too limiting |
| | need to generate and use local error in this context |
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Extensions

Adaptive resolution decision (in progress)

partition space into regions with own retention decision Evaluation using other wavelet functions

Apply wavelet transform to saved detail blocks

Save all details at lower res = 1 detail block at same res Implement more sophisticated error functions

Use existing visualization tool to experiment with error visualization

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