

Learning Inadmissible Heuristics During Search

Jordan Thayer, Austin Dionne, and Wheeler Ruml



UNIVERSITY *of* NEW HAMPSHIRE

`jtd7, ajv2, ruml at cs.unh.edu`

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and DARPA CSSG Grant N10AP20029

Heuristics Guide Search

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■ Heuristics

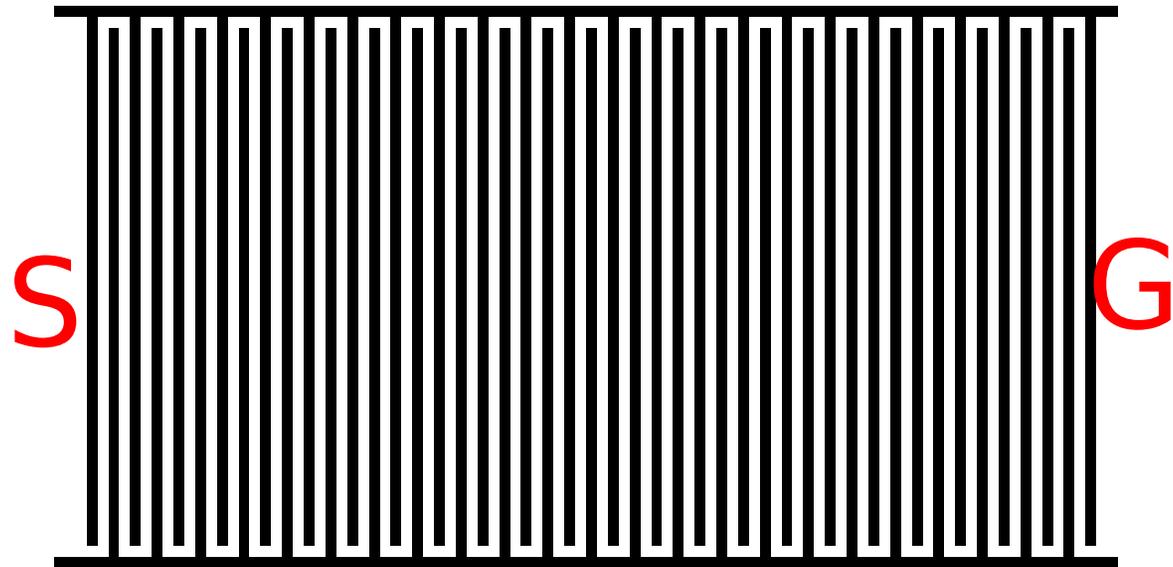
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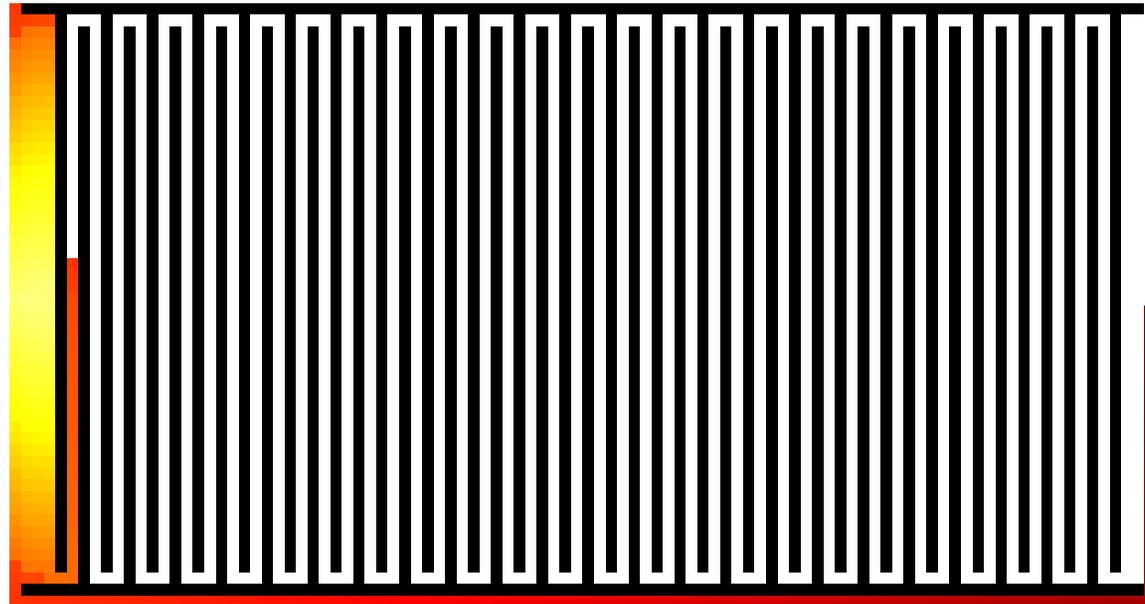
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greedy best-first search

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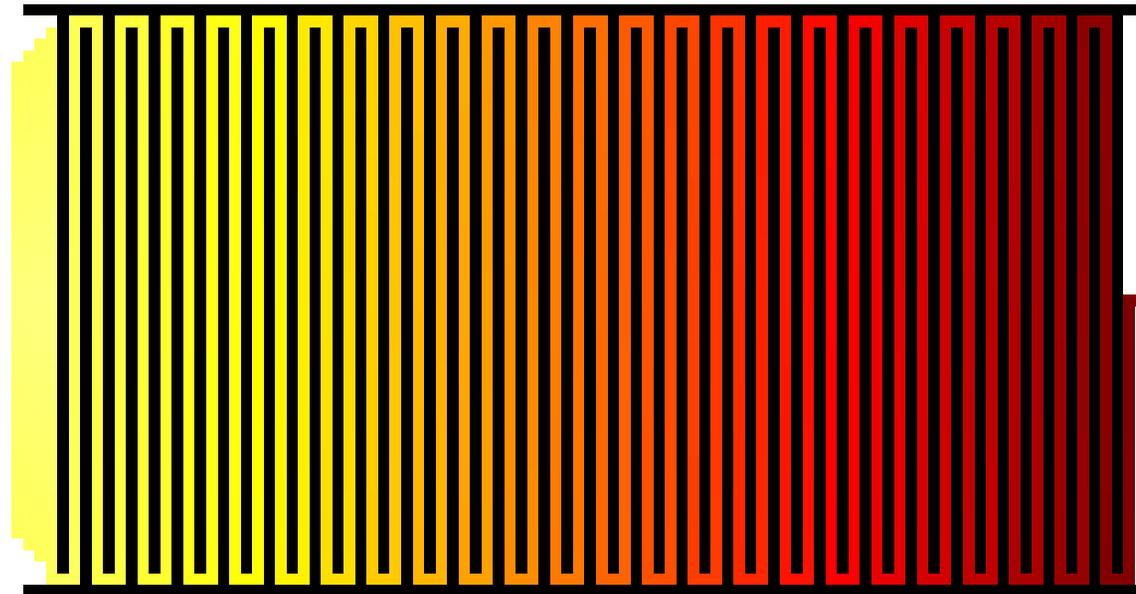
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greedy best-first search with learning

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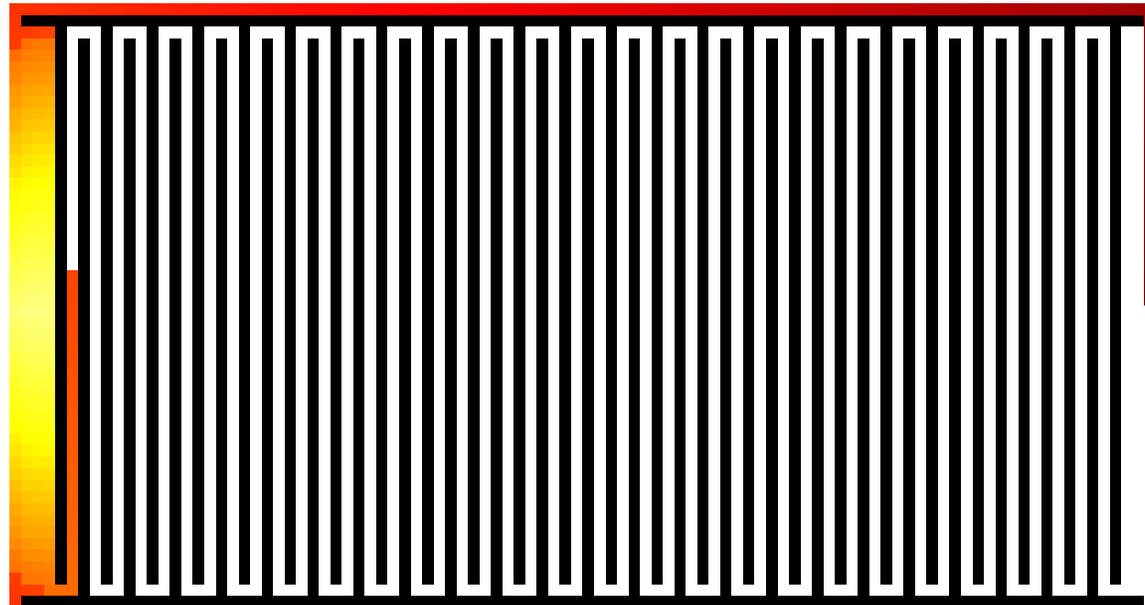
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- motivation
- building inadmissible heuristics during search
 - observing error
 - correcting for error
- performance of learned heuristics
 - suboptimal search - greedy best-first search
 - bounded suboptimal search - skeptical search

Motivation For Our Approach

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goal: **work out of the box on single instances**

- avoid offline training
- avoid domain specific features
- rely on data easily available in any best-first search

boost any suboptimal search

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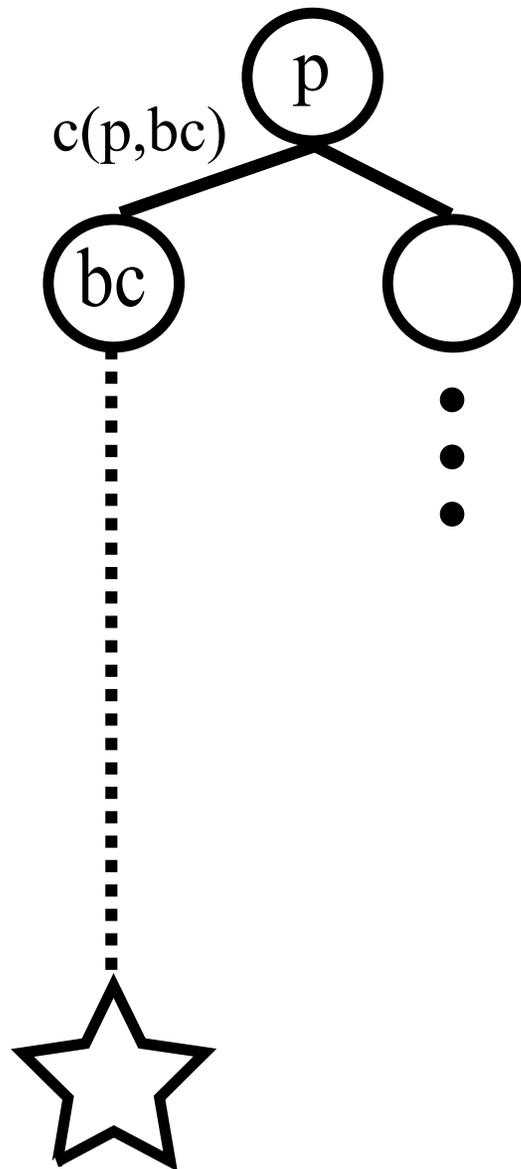
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Observing Error Between Parent and Best Child

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Observing Error Between Parent and Best Child

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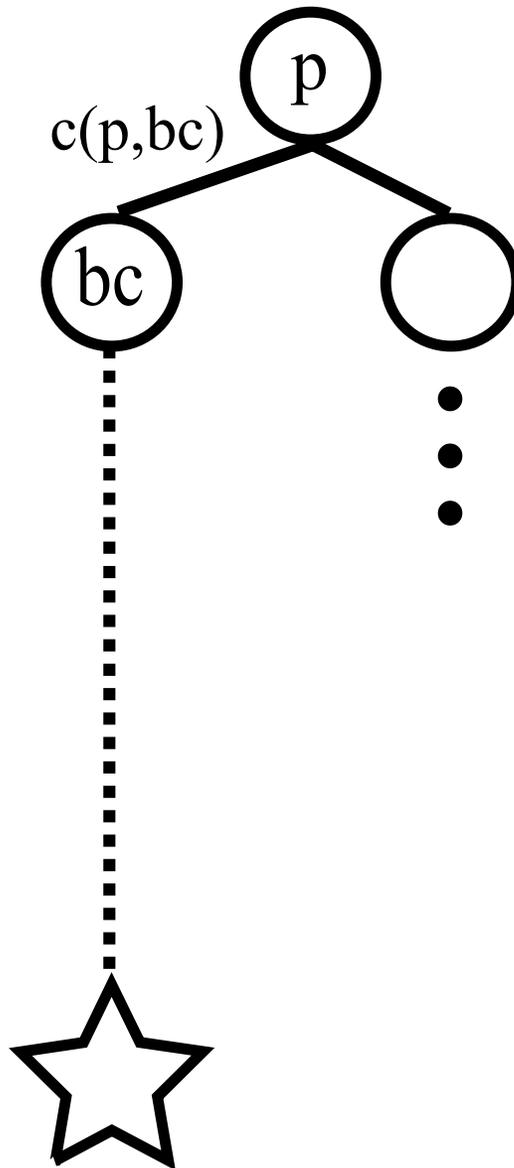
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$f(p)$ should equal $f(bc)$

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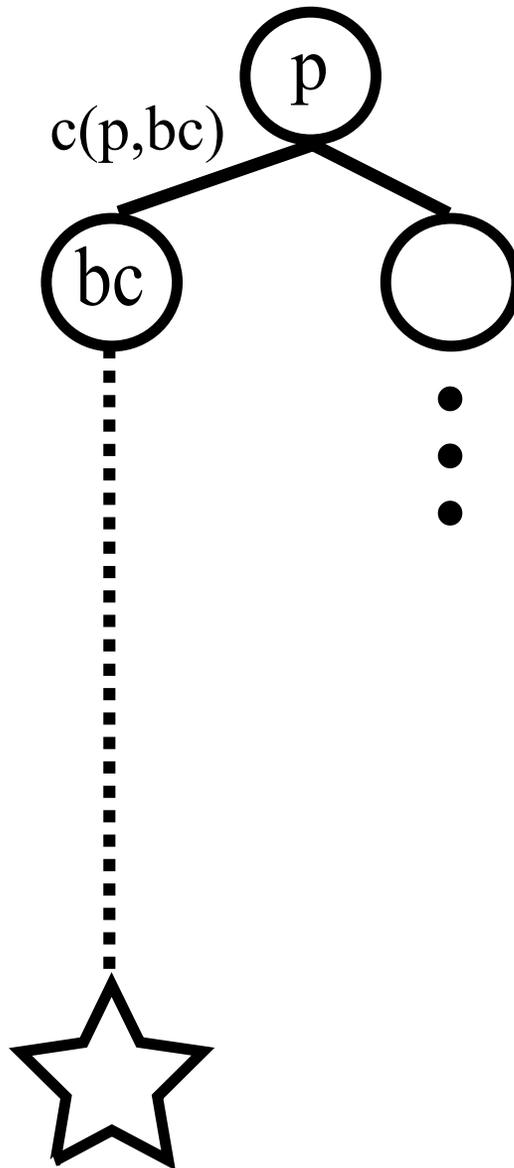
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$f(p)$ should equal $f(bc)$

$$f^*(p) = f^*(bc)$$

$$g(p) + h^*(p) = g(bc) + h^*(bc)$$

$$h^*(p) = h^*(bc) + c(p, bc)$$

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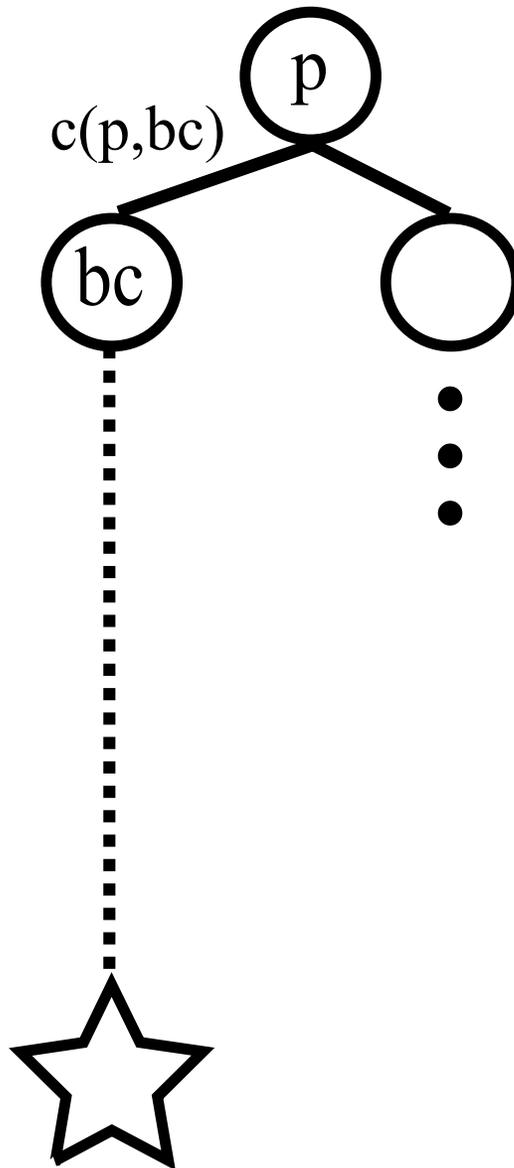
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$$h^*(p) = h^*(bc) + c(p, bc)$$

$$h(p) = h(bc) + c(p, bc) - \epsilon_h$$

$$\epsilon_h = h(bc) + c(p, bc) - h(p)$$

Observing Error Between Parent and Best Child

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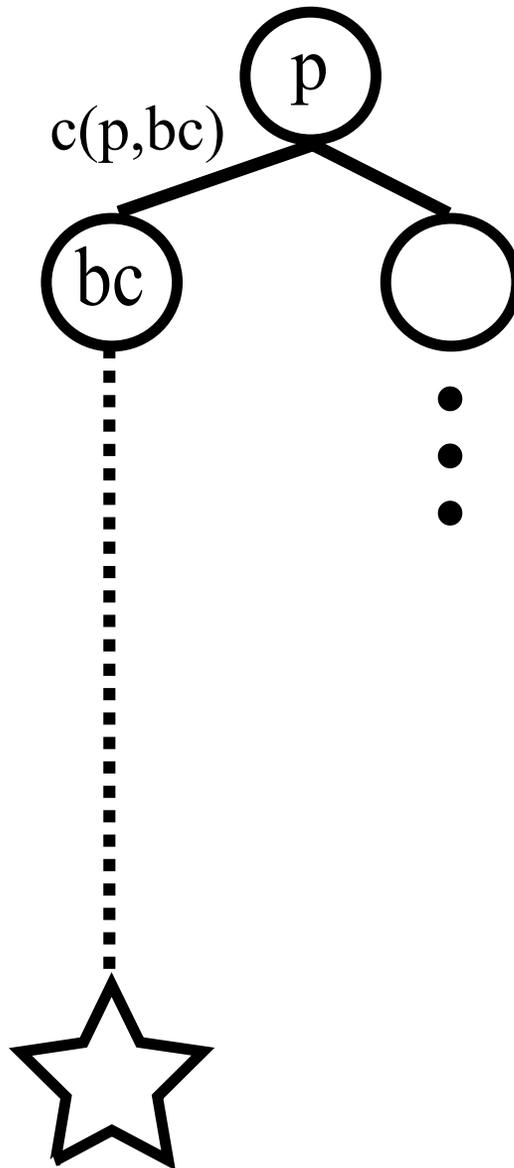
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$$h(p) = h(bc) + c(p, bc) - \epsilon_h$$

$$\epsilon_h = h(bc) + c(p, bc) - h(p)$$

$$\hat{h}(n) = h(n) + \bar{\epsilon}_h \cdot d(n)$$

$$\hat{\hat{h}}(n) = h(n) + \bar{\epsilon}_h \cdot \hat{d}(n)$$

Path Based Corrections

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$$\hat{h}(n) = h(n) + \bar{\epsilon}_h \cdot \hat{d}(n)$$

how do we estimate $\bar{\epsilon}_h$ from ϵ_h ?

simple global average

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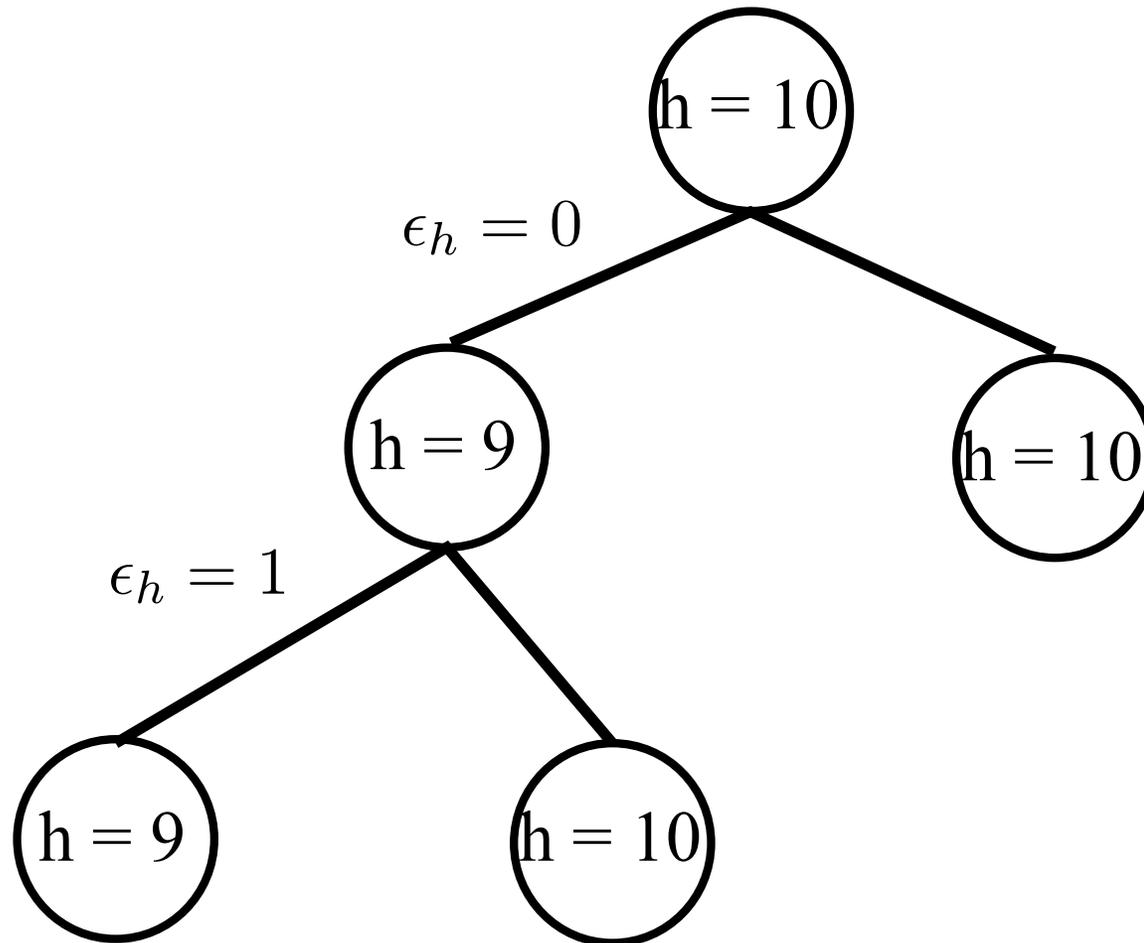
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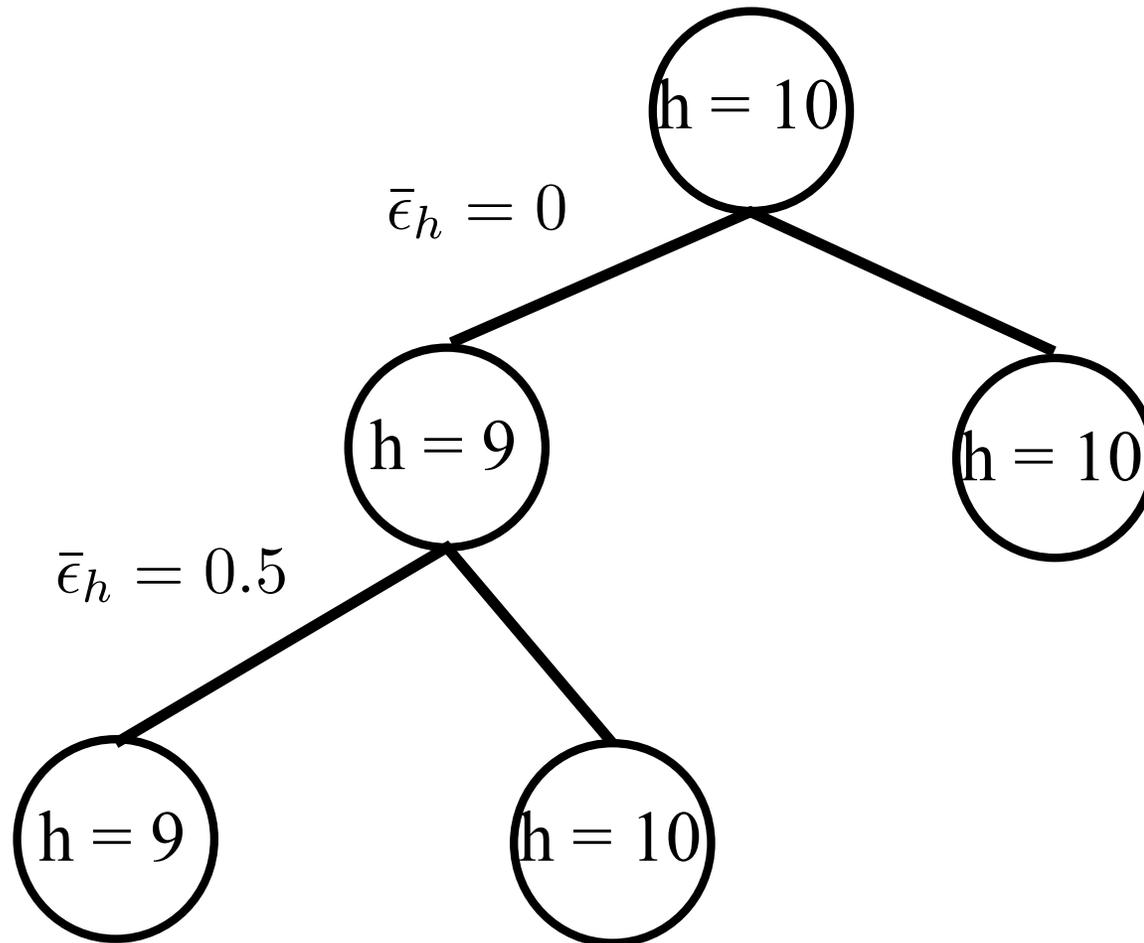
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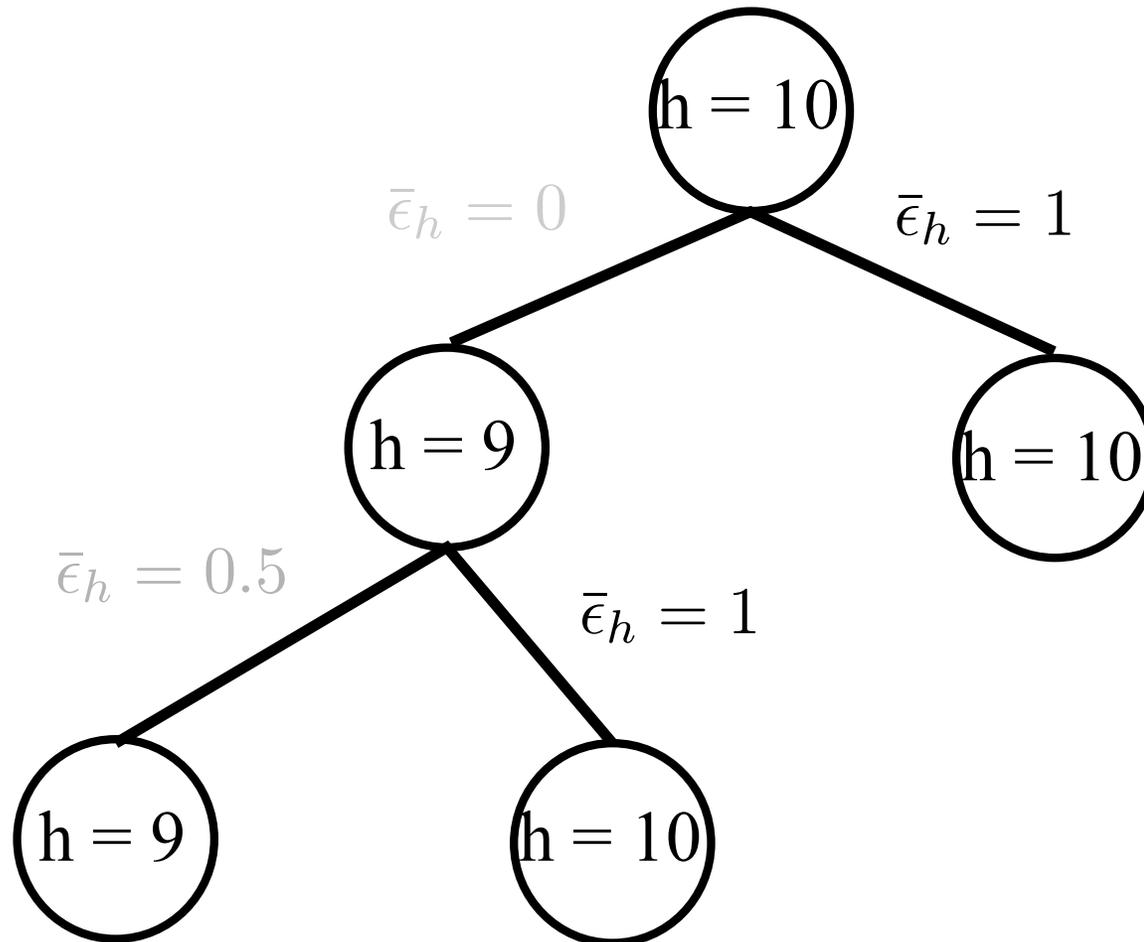
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$$\hat{h}(n) = h(n) + \bar{\epsilon}_h \cdot \hat{d}(n)$$

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- a parent and its best child should have same f
- every expansion provides information – use it!
- single step error can be measured during search
and we can use those corrections during that search

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■ Greedy Search

■ Bounded Quality

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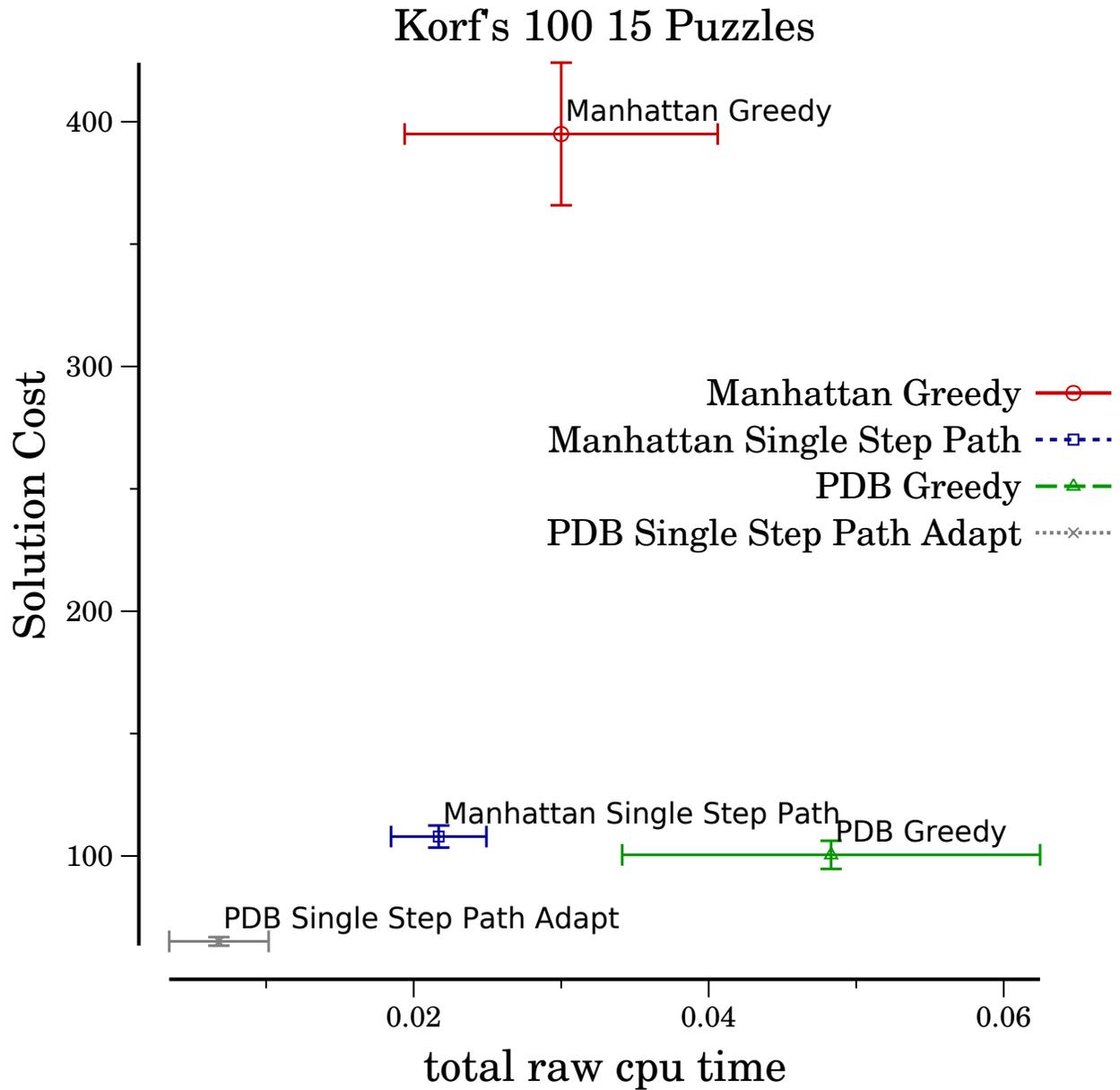
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 - bounded suboptimal – skeptical search

Greedy Best First Search

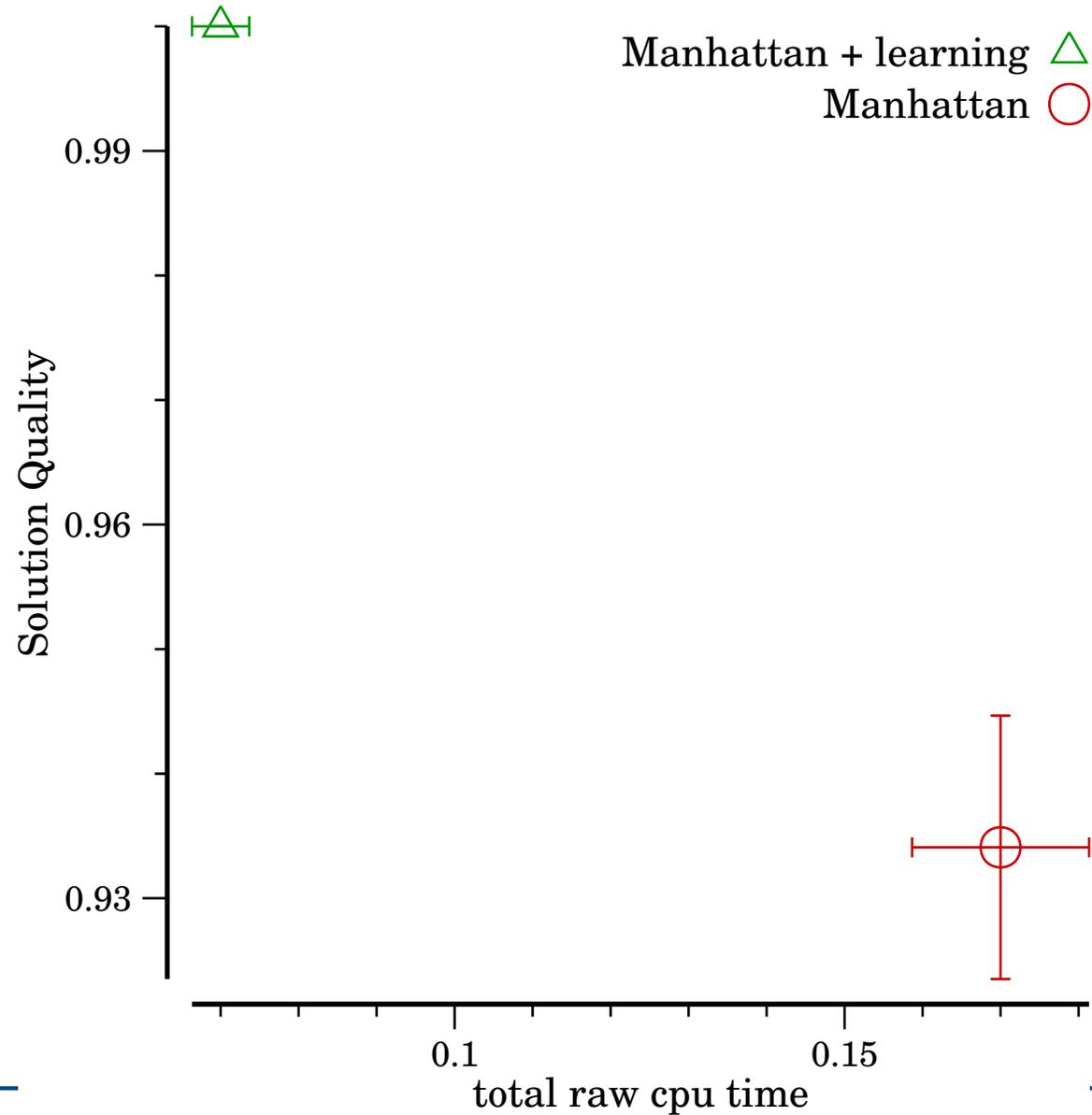
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Greedy Best First Search

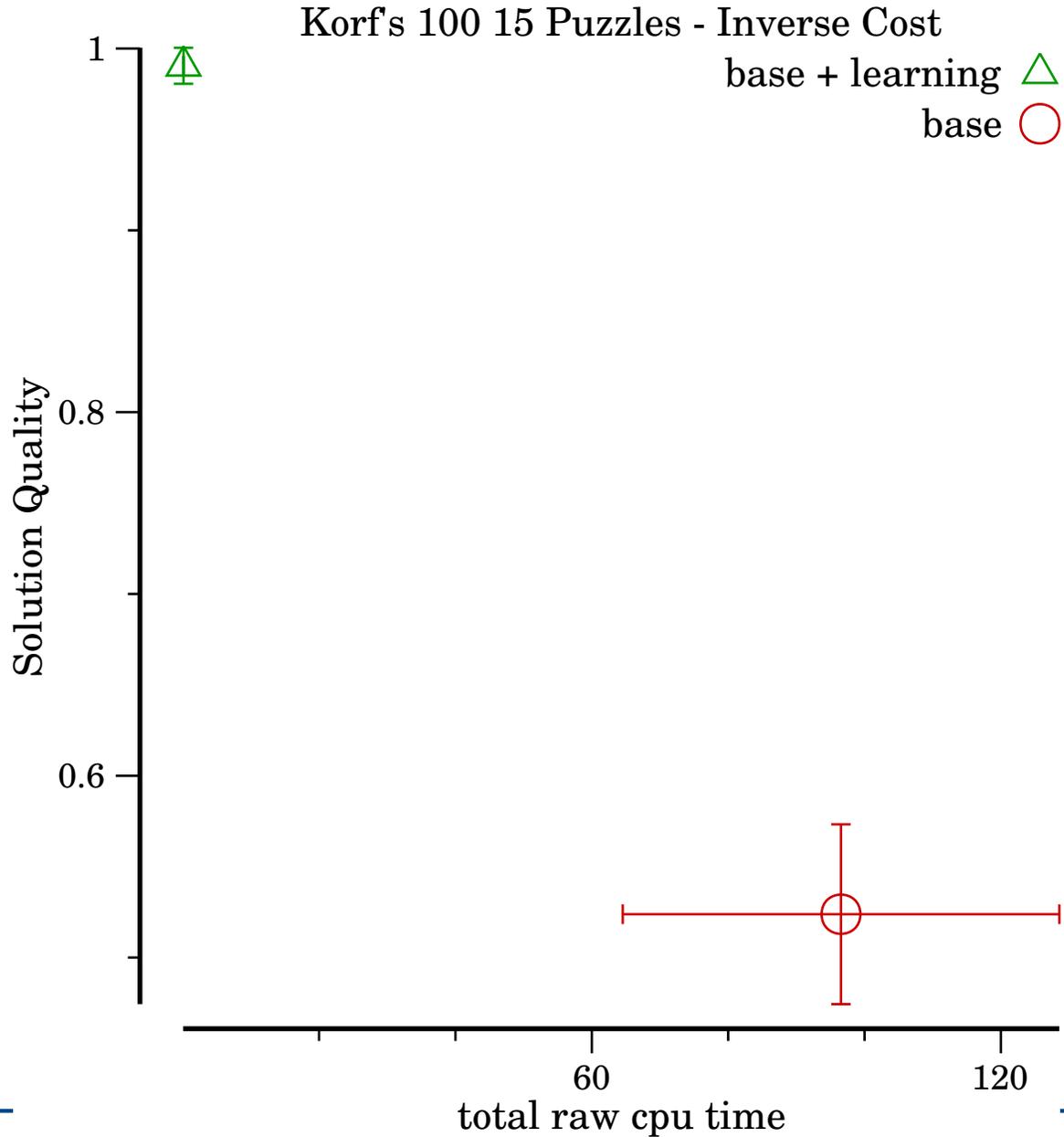
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Life Four-way Grids 35% Obstacles



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Bounded Suboptimal Search: Skeptical Search

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given a suboptimality bound w ,
find a solution within the bound as quickly as possible

Bounded Suboptimal Search: Skeptical Search

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given a suboptimality bound w ,
find a solution within the bound as quickly as possible
use optimistic framework (Thayer and Ruml, ICAPS-08):

1. run weighted A^* with an **inadmissible heuristic**

$$f'(n) = g(n) + w \cdot \hat{h}(n)$$

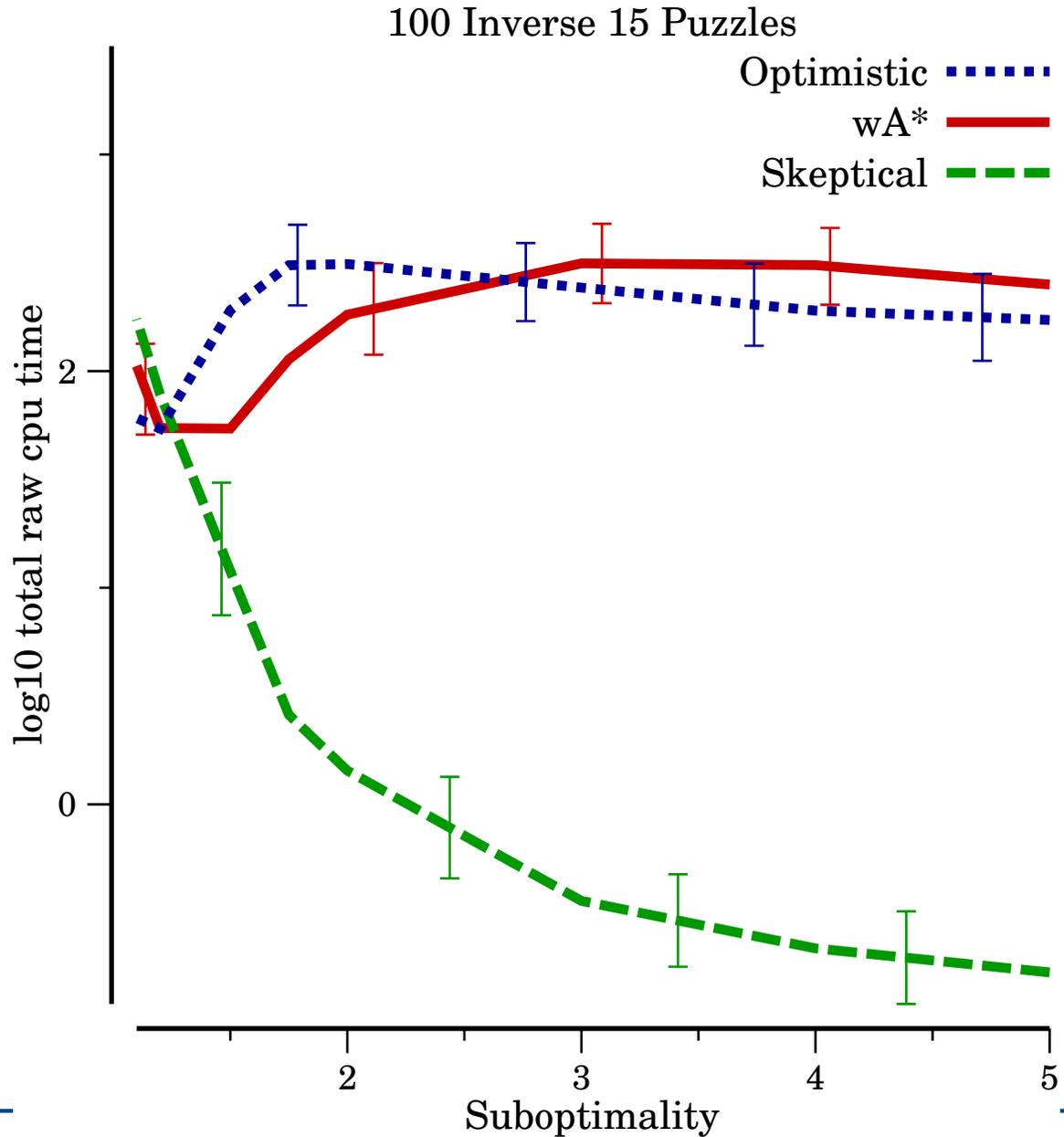
2. after a solution is found expand node with lowest f value
continue until $w \cdot f(best_f) \geq f(sol)$

this 'clean up' guarantees solution quality

(no ad hoc optimism parameter!)

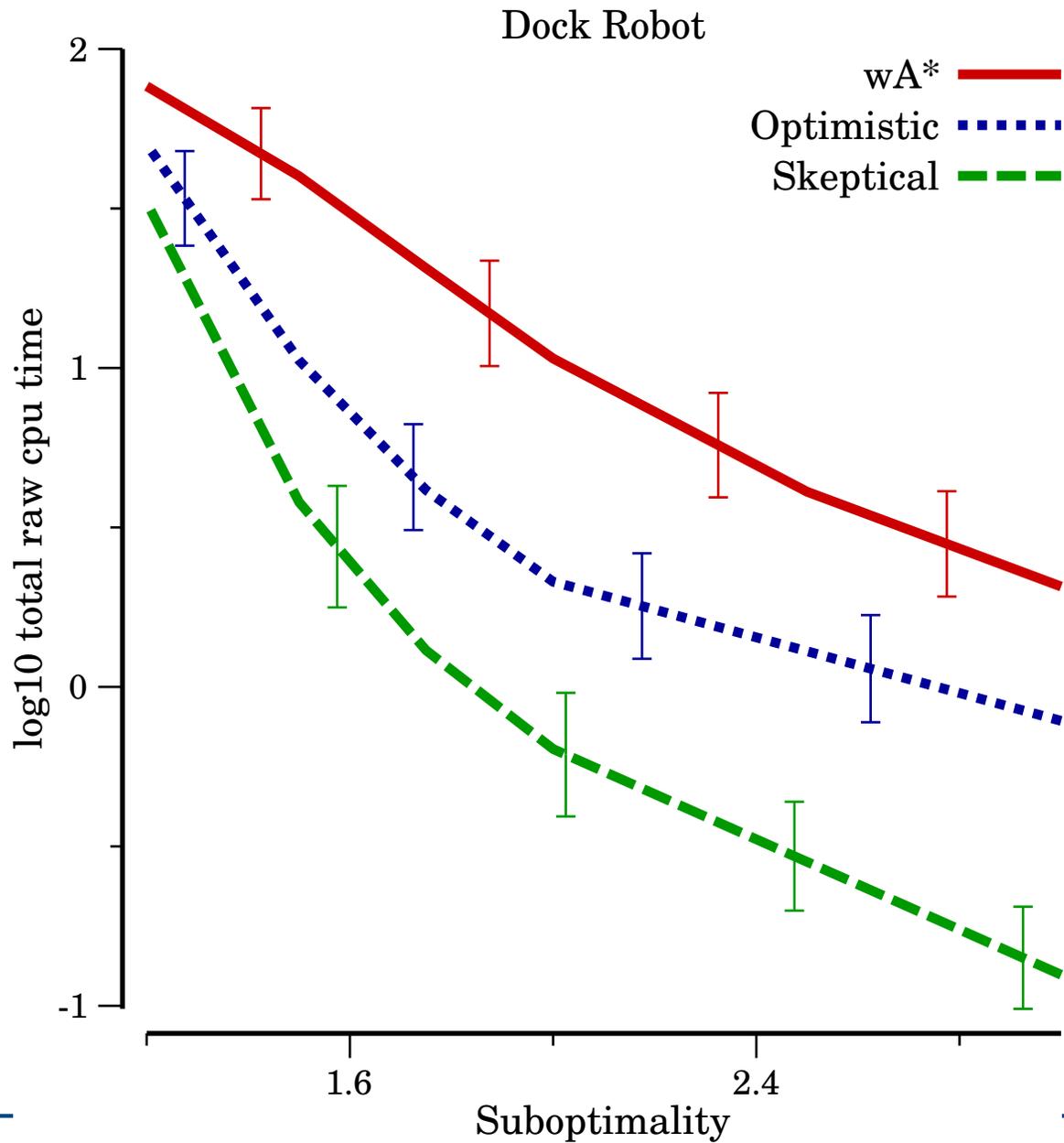
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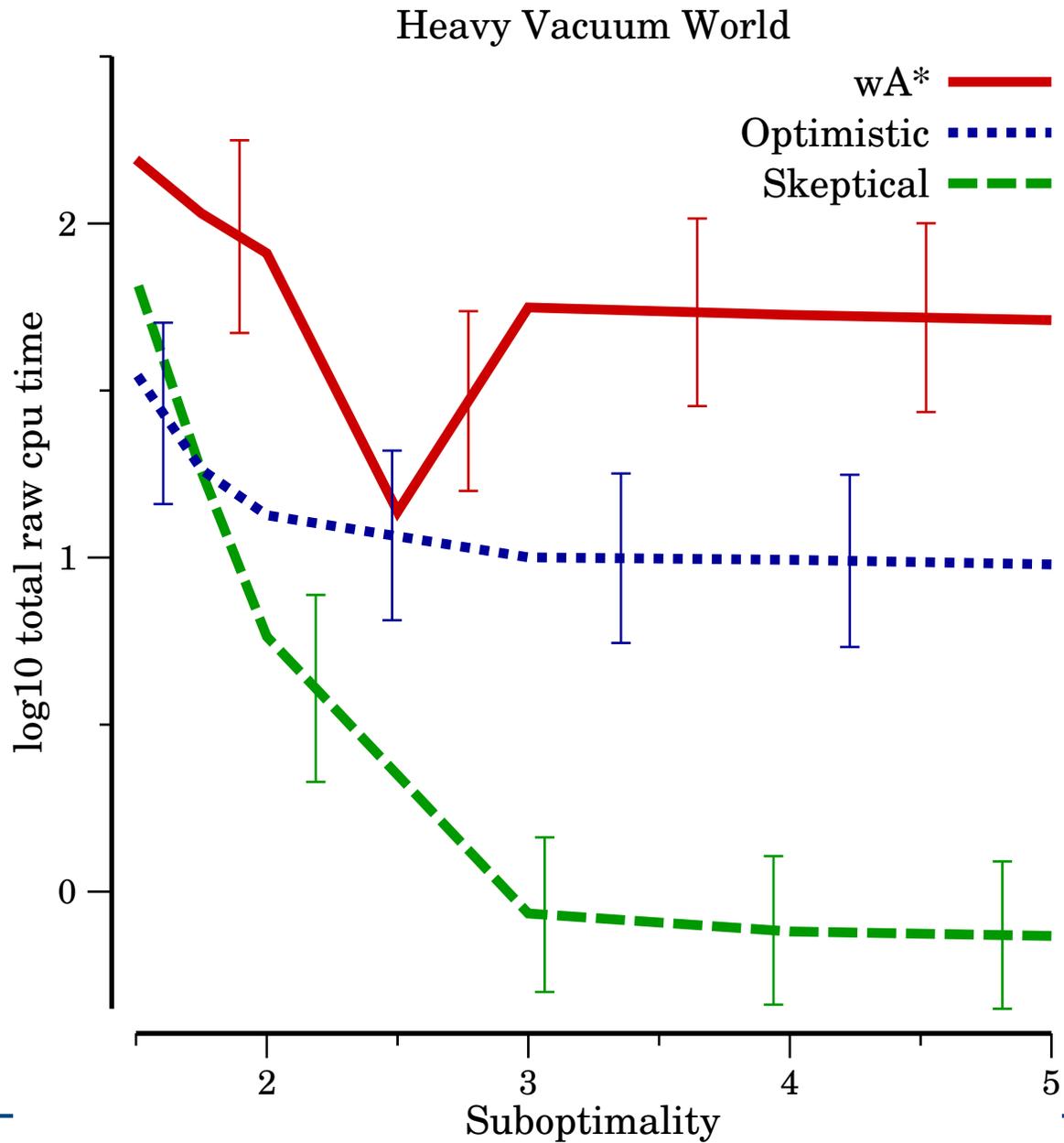
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In the Paper

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- accuracy less important than relative ordering
- instance specific learning truly beneficial
- distance estimates very helpful
for non-unit cost problems
- skeptical proof of bounded suboptimality

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■ In the Paper

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- we can learn inadmissible heuristics
 - these improve search guidance, make search go fast
- we can learn them online, during search
 - no dependence on domain specific information
 - no offline training
 - can learn instance specific correction
- skeptical search
 - removes parameter of optimistic search
 - state of the art performance

The University of New Hampshire

Tell your students to apply to grad school in CS at UNH!

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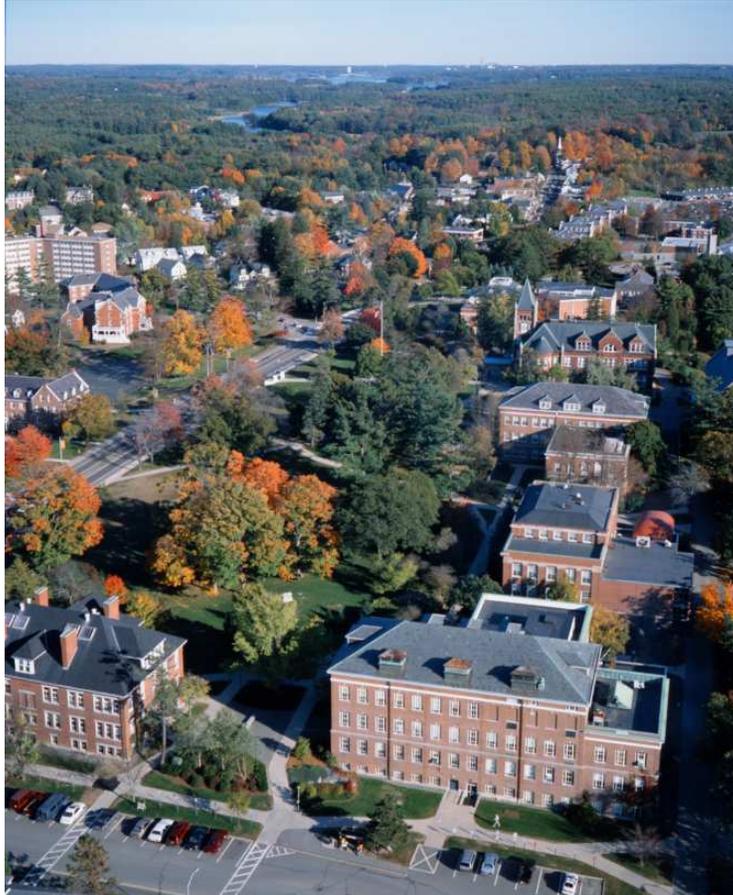
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- friendly faculty
- funding
- individual attention
- beautiful campus
- low cost of living
- easy access to Boston, White Mountains
- strong in AI, infoviz, networking, systems, bioinformatics

Heuristic Accuracy

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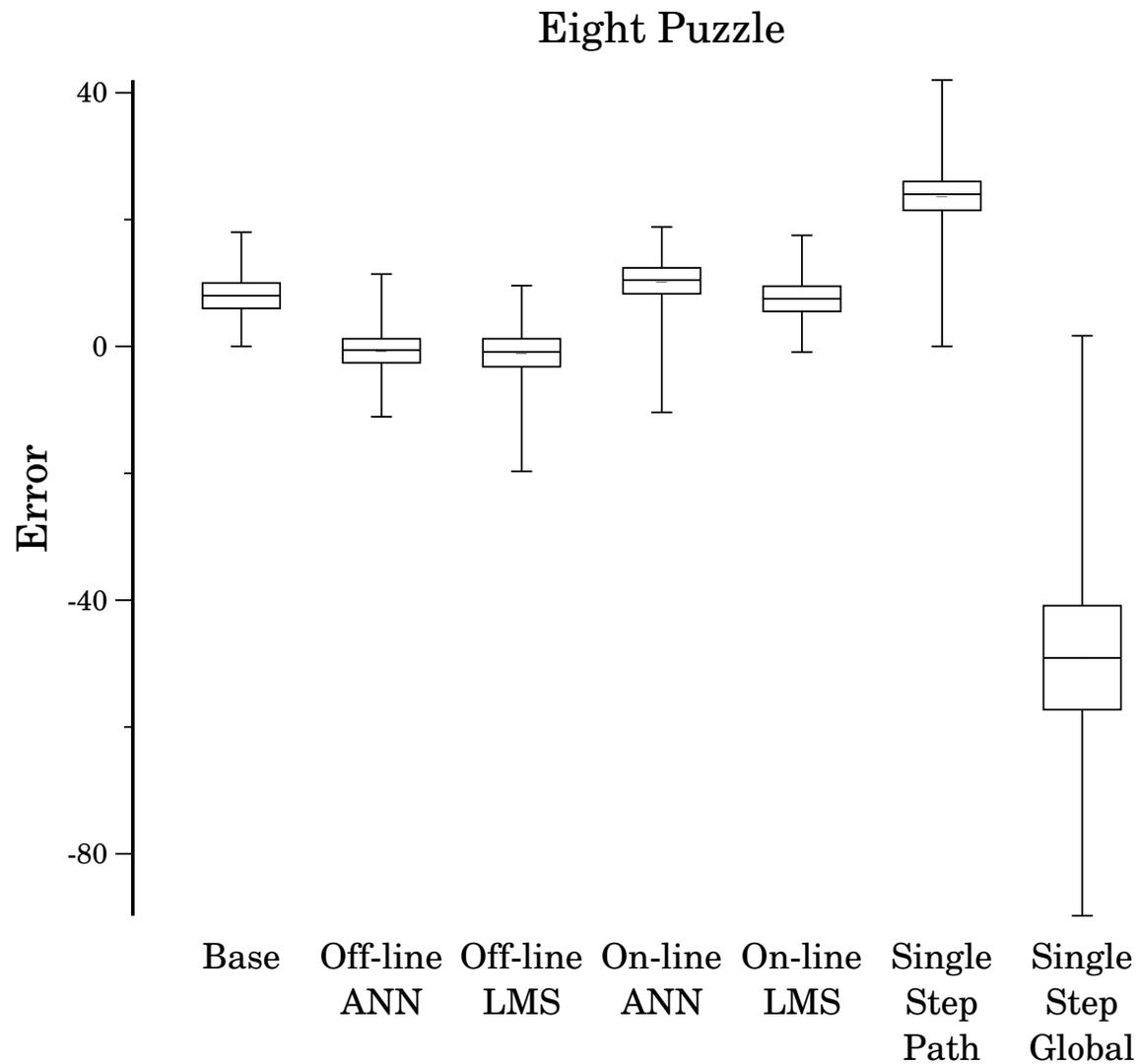
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■ Accuracy

■ Counter Example

■ Use d



It Doesn't Always Work

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■ Accuracy

■ Counter Example

■ Use *d*

11						
10	■	■				
9	8	■	■			
8	7	6	■	■		
7	6	5	4	■	■	
6	5	4	3	S	■	g

d Is Important!

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■ Accuracy

■ Counter Example

■ Use *d*

Life Four-way Grids 35% Obstacles

